# PHY131H1F <br> University of Toronto 

## Class 12 Preclass Video <br> by Jason Harlow

Based on Knight $3{ }^{\text {rd }}$ edition
Ch. 7, pgs. 167-184

## Interacting Objects



- When a hammer hits a nail, it exerts a forward force on the nail
- At the same time, the nail exerts a backward force on the hammer
- If you don't believe it, imagine hitting the nail with a glass hammer
- It's the force of the nail on the hammer that would cause the glass to shatter!


## Interacting Objects

- If object $A$ exerts a force on object $B$, then object $B$ exerts a force on object $A$.
- The pair of forces, as shown, is called an action/reaction pair.



## Section 7.1

## Objects, Systems and the Environment

- Chapters 5 and 6 considered forces acting on a single object, modeled as a particle
- The figure shows a diagram representing single-particle dynamics


This is a force diagram.

- We can use Newton's second law, $\vec{a}=\vec{F}_{\text {net }} / m$, to determine the particle's acceleration

Objects, Systems and the Environment

- For example, set:
- Object $\mathrm{A}=$ the hammer
- Object $\mathrm{B}=$ the nail
- Object $\mathrm{C}=$ the earth
- The earth interacts with both the hammer and the

Each line represents an interaction and an action/reaction pair of forces. Some pairs of objects, such as A and $B$, can have more than one interaction. naj viadidiny, the earth remains at rest while the hammer and the nail move

- Define the system as those objects whose motion we want to analyze
- Define the environment as objects external to the system


## Objects, Systems and the Environment

- In this chapter we extend the particle model to include two or more objects that interact
- The figure shows three objects interacting via action/reaction pairs of forces


Each line represents an interaction and an action/reaction pair of forces. Some pairs of objects, such as A and $B$, can have more than one interaction.

- The forces can be given labels, such as $\vec{F}_{\mathrm{A} \text { on } \mathrm{B}}$ and $\vec{F}_{\mathrm{B} \text { on } \mathrm{A}}$


## Objects, Systems and the Environment

- The figure shows a new kind of diagram, an interaction diagram
- The objects of the system are in a box
- Interactions are represented by lines connecting the objects


This is an interaction diagram.

- Interactions with objects in the environment are called external forces


## Propulsion

- If you try to walk across a frictionless floor, your foot slips and slides backward
- In order to walk, your foot must stick to the floor as you straighten your leg, moving your body forward
- The force that prevents slipping is static friction
- The static friction force points in the forward direction
- It is static friction that propels you forward!


What force causes this sprinter to accelerate?

## Examples of Propulsion



## Examples of Propulsion



The rocket pushes the hot gases backward. The gases push the rocket forward. Thrust force.

## Newton's Third Law

- Every force occurs as one member of an action/reaction pair of forces
- The two members of an action/reaction pair act on two different objects
- The two members of an action/reaction pair are equal in magnitude, but opposite in direction:

$$
\vec{F}_{\mathrm{A} \text { on } \mathrm{B}}=-\vec{F}_{\mathrm{B} \text { on } \mathrm{A}}
$$

- A catchy phrase, which is less precise, is:
"For every action there is an equal but opposite reaction."


## Examples of Propulsion



Reasoning with Newton's Third Law

- When you release a ball, it falls down
- The action/reaction forces of the ball and the earth are equal in magnitude
- The acceleration of the ball is

$$
\vec{a}_{\mathrm{B}}=\frac{\left(\vec{F}_{\mathrm{G}}\right)_{\mathrm{B}}}{m_{\mathrm{B}}}=-g \hat{\jmath}
$$

- The acceleration of the earth is


$$
\vec{a}_{\mathrm{E}}=\frac{\vec{F}_{\text {ball on carth }}}{m_{\mathrm{E}}}=\frac{m_{\mathrm{B}} g \hat{\jmath}}{m_{\mathrm{E}}}=\left(\frac{m_{\mathrm{B}}}{m_{\mathrm{E}}}\right) g \hat{\jmath}
$$

- If the ball has a mass of 1 kg , the earth accelerates upward at $2 \times 10^{-24} \mathrm{~m} / \mathrm{s}^{2}$


## Acceleration Constraints

- If two objects A and B move together, their accelerations are constrained to be equal: $a_{\mathrm{A}}=a_{\mathrm{B}}$
- This equation is called an acceleration constraint
- Consider a car being towed by a truck
- In this case, the
acceleration constraint is
$a_{\mathrm{C} x}=a_{\mathrm{T} x}=a_{x}$

- Because the accelerations of both objects are equal, we can drop the subscripts $C$ and T and call both of them $a_{x}$


## Acceleration Constraints



- But, as A moves to the right in the $+x$ direction, B moves down in the $-y$ direction
- In this case, the acceleration constraint is $a_{\mathrm{A} x}=-a_{\mathrm{B} y}$


## Tension Revisited



The Massless String Approximation


- Often in problems the mass of the string or rope is much less than the masses of the objects that it connects.
- In such cases, we can adopt the following massless string approximation:

$$
T_{\mathrm{B} \text { on } \mathrm{S}}=T_{\mathrm{A} \text { on } \mathrm{S}} \quad \text { (massless string approximation) }
$$

## The Massless String Approximation

- Two blocks are connected by a massless string, as block $B$ is pulled to the right - Forces $\vec{T}_{\text {Son A }}$ and $\vec{T}_{\text {Son B }}$ ac as if they are an action/reaction pair:

$$
\vec{T}_{\mathrm{S} \text { on } \mathrm{A}}=-\vec{T}_{\mathrm{S} \text { on } \mathrm{B}}
$$

We can omit the string if
we assume it is massless.

- All a massless string does is transmit a force from A to B without changing the magnitude of that force
- For problems in this book, you can assume that any strings or ropes are massless unless it explicitly states otherwise


## Pulleys

- Block B drags block A across a frictionless table as it falls
- The string and the pulley are both massless
- There is no friction where the pulley turns on its axle
- Therefore, $T_{\text {A on S }}=T_{\mathrm{B} \text { on } \mathrm{S}}$



## Pulleys

- Since $T_{\mathrm{A} \text { on B }}=T_{\mathrm{B} \text { on A }}$, we can draw the simplified free-body diagram on the right, below
- Forces $\vec{T}_{\mathrm{A} \text { on } \mathrm{B}}$ and $\vec{T}_{\mathrm{B} \text { on A }}$ act as if they are in an action/reaction pair, even though they are not opposite in direction because the tension force gets "turned" by the pulley


