

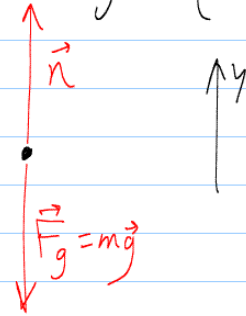
PHY131H1F Centre-screen notes
 Wednesday Oct. 10, 2012

free body diagram (f.b.d.)
 of car:



$$\vec{a} = 0$$

$$\Rightarrow \vec{F}_{\text{net}} = 0$$

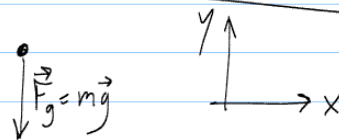


$$(F_{\text{net}})_y = n - mg = 0$$

$$n = mg$$

$$a = \frac{F_{\text{net}}}{m}$$

f.b.d. of angry bird:

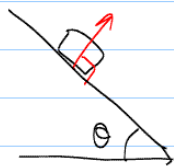


	x	y
\vec{F}_g	0	-mg
\vec{F}_{net}	0	-mg

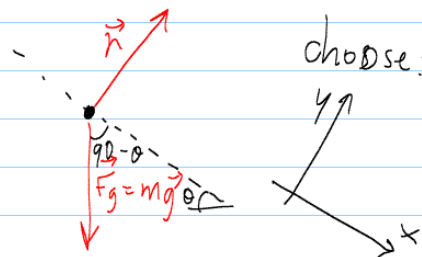
$$(F_{\text{net}})_x = 0 \Rightarrow a_x = 0$$

$$(F_{\text{net}})_y = m a_y = -mg$$

$$a_y = -g \leftarrow \text{Eq. 2.25!}$$



f.b.d. of
 cart:

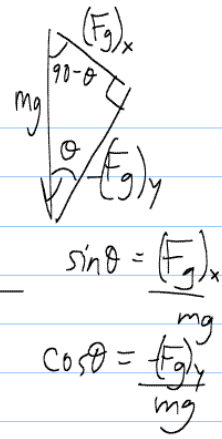


choose:

→ we know cart stays on track:

$\Rightarrow a_y = 0$
 \rightarrow We want to find a_x

	x	y
T		
F_g	$mg \sin \theta$	$-mg \cos \theta$
F_{Net}	0	n
	$mg \sin \theta$	$-mg \cos \theta + n$



$$(F_{Net})_x = \cancel{m} a_x = \cancel{m} g \sin \theta$$

$$\boxed{a_x = g \sin \theta} \leftarrow \text{Eq. 2.26!}$$

Also, Note that: $(F_{Net})_y = 0 = -mg \cos \theta + n$

$$\Rightarrow \boxed{n = mg \cos \theta} \leftarrow \text{could be useful??}$$

Fbd.



$\uparrow \vec{a} \leftarrow$ towards centre of circular path.

$\uparrow \vec{F}_{Net}$ must be up.

$\vec{T} + \vec{F}_g$ must be up.

$$T > F_g$$