

PHY131H1F  
University of Toronto  
Class 7 Preclass Video  
by Jason Harlow

## Section 4.1

Based on Knight 3<sup>rd</sup> edition  
Ch. 4, sections 4.1 to 4.4,  
pgs. 85-97

### Acceleration

The *average acceleration* of a moving object is defined as the vector:

$$\vec{a}_{\text{avg}} = \frac{\Delta \vec{v}}{\Delta t}$$

The acceleration  $\vec{a}$  **points in the same direction as  $\Delta \vec{v}$** , the change in velocity

As an object moves, its velocity vector can change in two possible ways:

1. The magnitude of the velocity can change, indicating a change in speed, or
2. The direction of the velocity can change, indicating that the object has changed direction.

### Tactics: Finding the acceleration vector

#### TACTICS BOX 4.1 Finding the acceleration vector

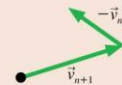
To find the acceleration between velocity  $\vec{v}_n$  and velocity  $\vec{v}_{n+1}$ :



- 1 Draw the velocity vector  $\vec{v}_{n+1}$ .

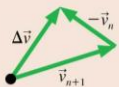


- 2 Draw  $-\vec{v}_n$  at the tip of  $\vec{v}_{n+1}$ .

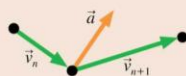


### Tactics: Finding the acceleration vector

- 3 Draw  $\Delta \vec{v} = \vec{v}_{n+1} - \vec{v}_n = \vec{v}_{n+1} + (-\vec{v}_n)$   
This is the direction of  $\vec{a}$ .

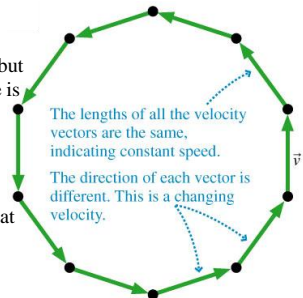


- 4 Return to the original motion diagram. Draw a vector at the middle point in the direction of  $\Delta \vec{v}$ ; label it  $\vec{a}$ . This is the average acceleration between  $\vec{v}_n$  and  $\vec{v}_{n+1}$ .



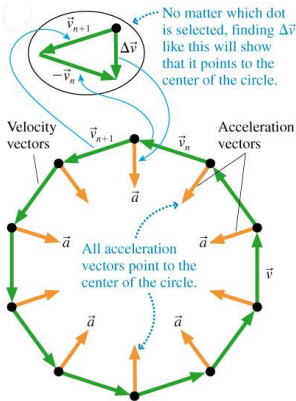
### Acceleration

- The figure to the right shows a motion diagram of Maria riding a Ferris wheel
- Maria has constant speed but *not* constant velocity, so she is accelerating.
- For every pair of adjacent velocity vectors, we can subtract them to find the average acceleration near that point



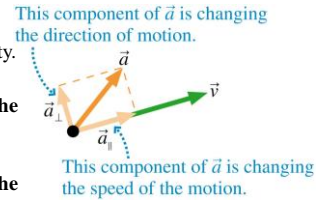
### Acceleration

- At every point Maria's acceleration points toward the center of the circle.
- This is an acceleration due to changing direction, not to changing speed.



### Analyzing the acceleration vector

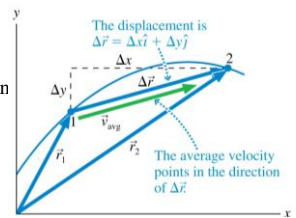
- An object's acceleration can be decomposed into components parallel and perpendicular to the velocity.
- $\vec{a}_{\parallel}$  is the piece of the acceleration that causes the object to change speed
- $\vec{a}_{\perp}$  is the piece of the acceleration that causes the object to change direction
- An object changing direction *always* has a component of acceleration perpendicular to the direction of motion.



## Section 4.2

### Two-Dimensional Kinematics

- The figure to the right shows the *trajectory* of a particle moving in the  $x$ - $y$  plane
- The particle moves from position  $\vec{r}_1$  at time  $t_1$  to position  $\vec{r}_2$  at a later time  $t_2$
- The average velocity points in the direction of the displacement  $\Delta\vec{r}$  and is



$$\vec{v}_{\text{avg}} = \frac{\Delta\vec{r}}{\Delta t} = \frac{\Delta x}{\Delta t}\hat{i} + \frac{\Delta y}{\Delta t}\hat{j}$$

### Two-Dimensional Kinematics

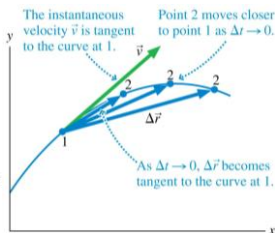
- The instantaneous velocity is the limit of  $\vec{v}_{\text{avg}}$  as  $\Delta t \rightarrow 0$
- As shown the instantaneous velocity vector is tangent to the trajectory
- Mathematically:

$$\vec{v} = \lim_{\Delta t \rightarrow 0} \frac{\Delta\vec{r}}{\Delta t} = \frac{d\vec{r}}{dt} = \frac{dx}{dt}\hat{i} + \frac{dy}{dt}\hat{j}$$

which can be written:

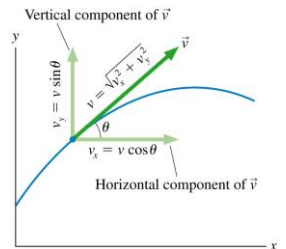
$$\vec{v} = v_x\hat{i} + v_y\hat{j}$$

where:  $v_x = \frac{dx}{dt}$  and  $v_y = \frac{dy}{dt}$



### Two-Dimensional Kinematics

- If the velocity vector's angle  $\theta$  is measured from the positive  $x$ -direction, the velocity components are
- $$v_x = v \cos \theta$$
- $$v_y = v \sin \theta$$
- where the particle's *speed* is
- $$v = \sqrt{v_x^2 + v_y^2}$$

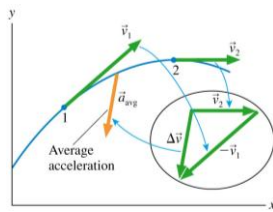


- Conversely, if we know the velocity components, we can determine the direction of motion:

$$\tan \theta = \frac{v_y}{v_x}$$

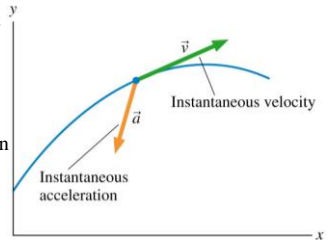
### Two-Dimensional Acceleration

- The figure to the right shows the trajectory of a particle moving in the  $x$ - $y$  plane
- The instantaneous velocity is  $\vec{v}_1$  at time  $t_1$  and  $\vec{v}_2$  at a later time  $t_2$
- We can use vector subtraction to find  $\vec{a}_{\text{avg}}$  during the time interval  $\Delta t = t_2 - t_1$



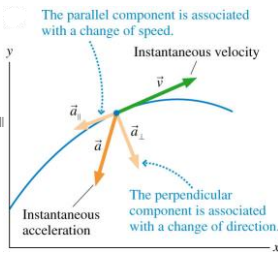
### Two-Dimensional Acceleration

- The *instantaneous acceleration* is the limit of  $\vec{a}_{\text{avg}}$  as  $\Delta t \rightarrow 0$ .
- The instantaneous acceleration vector is shown along with the instantaneous velocity in the figure.
- By definition,  $\vec{a}$  is the rate at which  $\vec{v}$  is changing at that instant.



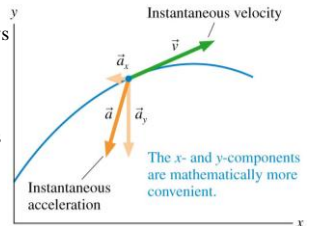
### Decomposing Two-Dimensional Acceleration

- The figure to the right shows the trajectory of a particle moving in the  $x$ - $y$  plane
- The acceleration  $\vec{a}$  is decomposed into components  $\vec{a}_{\parallel}$  and  $\vec{a}_{\perp}$
- $\vec{a}_{\parallel}$  is associated with a change in speed
- $\vec{a}_{\perp}$  is associated with a change of direction
- $\vec{a}_{\perp}$  always points toward the “inside” of the curve because that is the direction in which  $\vec{v}$  is changing



### Decomposing Two-Dimensional Acceleration

- The figure to the right shows the trajectory of a particle moving in the  $x$ - $y$  plane
- The acceleration  $\vec{a}$  is decomposed into components  $a_x$  and  $a_y$



- If  $v_x$  and  $v_y$  are the  $x$ - and  $y$ - components of velocity, then

$$a_x = \frac{dv_x}{dt} \quad \text{and} \quad a_y = \frac{dv_y}{dt}$$

### Constant Acceleration

- If the acceleration  $\vec{a} = a_x \hat{i} + a_y \hat{j}$  is constant, then the two components  $a_x$  and  $a_y$  are both constant
- In this case, everything from Chapter 2 about constant-acceleration kinematics applies to the *components*
- The  $x$ -components and  $y$ -components of the motion can be treated independently
- They remain connected through the fact that  $\Delta t$  must be the same for both

$$\begin{aligned} x_f &= x_i + v_{ix} \Delta t + \frac{1}{2} a_x (\Delta t)^2 & y_f &= y_i + v_{iy} \Delta t + \frac{1}{2} a_y (\Delta t)^2 \\ v_{fx} &= v_{ix} + a_x \Delta t & v_{fy} &= v_{iy} + a_y \Delta t \end{aligned}$$

## Section 4.3

### Projectile Motion

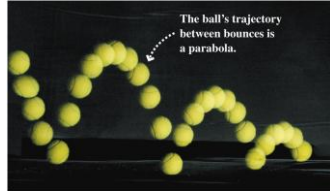
Baseballs, tennis balls, Olympic divers, etc, all exhibit *projectile motion*

A **projectile** is an object that moves in two dimensions under the influence of *only* gravity

Projectile motion extends the idea of free-fall motion to include a horizontal component of velocity

Air resistance is neglected

Projectiles in two dimensions follow a *parabolic trajectory* as shown in the photo



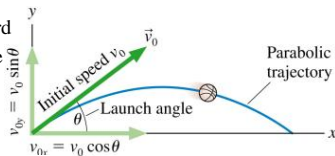
### Projectile Motion

Gravity acts downward  
Therefore, a projectile has no horizontal acceleration

Thus  
 $a_x = 0$

$a_y = -g$

- The vertical component of acceleration  $a_y$  is  $-g$  of free fall
- The horizontal component of  $a_x$  is zero
- Projectiles are in free fall

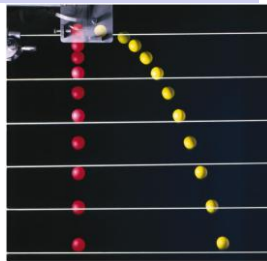


(projectile motion)

### Reasoning About Projectile Motion

A heavy ball is launched exactly horizontally at height  $h$  above a horizontal field. At the exact instant that the ball is launched, a second ball is simply dropped from height  $h$ . Which ball hits the ground first?

- If air resistance is neglected, the balls hit the ground *simultaneously*
- The initial horizontal velocity of the first ball has *no* influence over its vertical motion
- Neither ball has any initial vertical motion, so both fall distance  $h$  in the same amount of time



### Projectile Motion

The start of a projectile's motion is called the *launch*

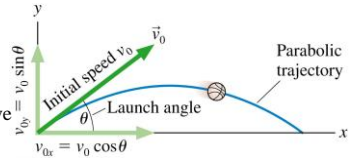
The angle  $\theta$  of the initial velocity  $v_0$  above the  $x$ -axis is called the **launch angle**

The initial velocity vector can be broken into components

$$v_{0x} = v_0 \cos \theta$$

$$v_{0y} = v_0 \sin \theta$$

where  $v_0$  is the initial speed



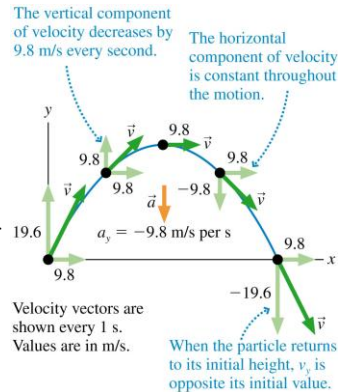
### Projectile Motion

The figure shows a projectile launched from the origin with initial velocity

$$\vec{v}_0 = (9.8\hat{i} + 19.6\hat{j}) \text{ m/s}$$

The value of  $v_x$  never changes because there's no horizontal acceleration

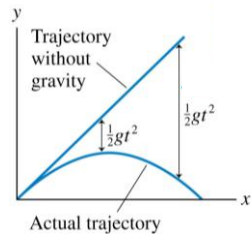
$v_y$  decreases by 9.8 m/s every second



### Reasoning About Projectile Motion

A hunter in the jungle wants to shoot down a coconut that is hanging from the branch of a tree. He points his arrow directly at the coconut, but the coconut falls from the branch at the *exact* instant the hunter shoots the arrow. Does the arrow hit the coconut?

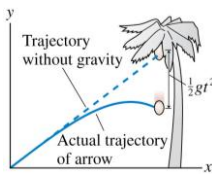
- Without gravity, the arrow would follow a straight line
- Because of gravity, the arrow at time  $t$  has "fallen" a distance  $\frac{1}{2}gt^2$  below this line
- The separation grows as  $\frac{1}{2}gt^2$ , giving the trajectory its parabolic shape



### Reasoning About Projectile Motion

A hunter in the jungle wants to shoot down a coconut that is hanging from the branch of a tree. He points his arrow directly at the coconut, but the coconut falls from the branch at the *exact* instant the hunter shoots the arrow. Does the arrow hit the coconut?

- Had the coconut stayed on the tree, the arrow would have curved under its target as gravity cases it to fall a distance  $\frac{1}{2}gt^2$  below the straight line
- But  $\frac{1}{2}gt^2$  is also the distance the coconut falls while the arrow is in flight
- So yes, the arrow hits the coconut!



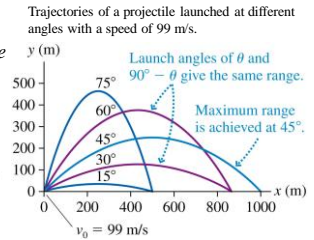
### Range of a Projectile

A projectile with initial speed  $v_0$  has a launch angle of  $\theta$  above the horizontal. How far does it travel over level ground before it returns to the same elevation from which it was launched?

- This distance is sometimes called the *range* of a projectile
- Example 4.5 from your textbook shows:

$$\text{distance} = \frac{v_0^2 \sin(2\theta)}{g}$$

- The maximum distance occurs for  $\theta = 45^\circ$



#### PROBLEM-SOLVING STRATEGY 4.1 Projectile motion problems

**MODEL** Make simplifying assumptions, such as treating the object as a particle. Is it reasonable to ignore air resistance?

**VISUALIZE** Use a pictorial representation. Establish a coordinate system with the  $x$ -axis horizontal and the  $y$ -axis vertical. Show important points in the motion on a sketch. Define symbols and identify what the problem is trying to find.

**SOLVE** The acceleration is known:  $a_x = 0$  and  $a_y = -g$ . Thus the problem is one of two-dimensional kinematics. The kinematic equations are

$$\begin{aligned} x_f &= x_i + v_{ix} \Delta t & y_f &= y_i + v_{iy} \Delta t - \frac{1}{2}g(\Delta t)^2 \\ v_{fx} &= v_{ix} = \text{constant} & v_{fy} &= v_{iy} - g \Delta t \end{aligned}$$

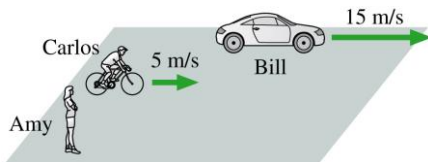
$\Delta t$  is the same for the horizontal and vertical components of the motion. Find  $\Delta t$  from one component, then use that value for the other component.

**ASSESS** Check that your result has the correct units, is reasonable, and answers the question.

## Section 4.4

### Relative Motion

- The figure below shows Amy and Bill watching Carlos on his bicycle
- According to Amy, Carlos's velocity is  $(v_x)_{CA} = +5 \text{ m/s}$
- The CA subscript means "C relative to A"
- According to Bill, Carlos's velocity is  $(v_x)_{CB} = -10 \text{ m/s}$
- Every velocity is measured *relative* to a certain observer
- There is no "true" velocity



### Relative Motion

- The velocity of C relative to B is the velocity of C relative to A *plus* the velocity of A relative to B

The first subscript is the same on both sides. The last subscript is the same on both sides.

$$(v_x)_{CB} = (v_x)_{CA} + (v_x)_{AB}$$

The inner subscripts "cancel."

- If B is moving to the right relative to A, then A is moving to the left relative to B
- Therefore,  $(v_x)_{AB} = -(v_x)_{BA}$

## Reference Frames

▪ A coordinate system in which an experimenter makes position measurements is called a **reference frame**

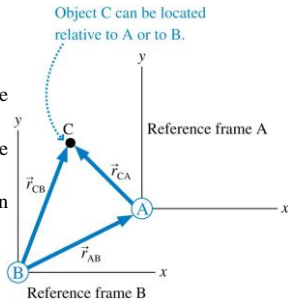
▪ In the figure, Object C is measured in two different reference frames, A and B

▪  $\vec{r}_{CA}$  is the position of C relative to the origin of A

▪  $\vec{r}_{CB}$  is the position of C relative to the origin of B

▪  $\vec{r}_{AB}$  is the position of the origin of A relative to the origin of B

$$\vec{r}_{CB} = \vec{r}_{CA} + \vec{r}_{AB}$$



## Reference Frames

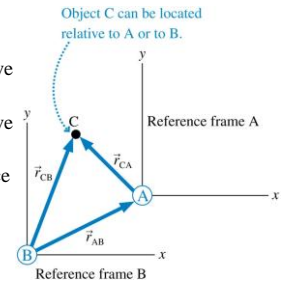
▪ Relative velocities are found as the time derivative of the relative positions

▪  $\vec{v}_{CA}$  is the velocity of C relative to A

▪  $\vec{v}_{CB}$  is the velocity of C relative to B

▪  $\vec{v}_{AB}$  is the velocity of reference frame A relative to reference frame B

$$\vec{v}_{CB} = \vec{v}_{CA} + \vec{v}_{AB}$$



▪ This is known as the **Galilean transformation of velocity**