

PHY131H1F
University of Toronto
Class 8 Preclass Video
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Section 4.5

Based on Knight 3rd edition
Ch. 4, sections 4.5 to 4.7,
pgs. 98-108

Circular Motion

- Consider a ball on a roulette wheel
- It moves along a circular path of radius r
- Other examples of circular motion are a satellite in an orbit, or a ball on the end of a string
- Circular motion is an example of two-dimensional motion in a plane



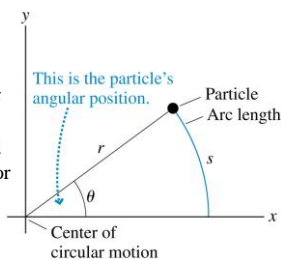
Angular Position

- Consider a particle at a distance r from the origin, at an angle θ from the positive x axis
- The angle may be measured in degrees, revolutions (rev) or **radians** (rad), that are related by:

$$1 \text{ rev} = 360^\circ = 2\pi \text{ rad}$$

- If the angle is measured in radians, then there is a simple relation between θ and the **arc length** s that the particle travels along the edge of a circle of radius r :

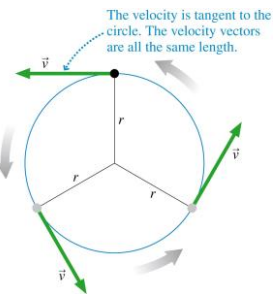
$$s = r\theta \quad (\text{with } \theta \text{ in rad})$$



Uniform Circular Motion

- To begin the study of circular motion, consider a particle that moves at *constant speed* around a circle of radius r
- This is called **uniform circular motion**
- The time interval to complete one revolution is called the period, T
- The period T is related to the speed v :

$$v = \frac{1 \text{ circumference}}{1 \text{ period}} = \frac{2\pi r}{T}$$



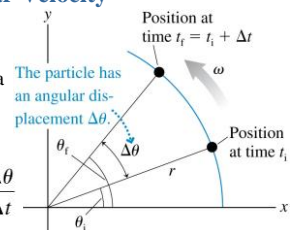
Angular Velocity

- A particle on a circular path moves through an **angular displacement** $\Delta\theta = \theta_f - \theta_i$ in a time interval $\Delta t = t_f - t_i$
- In analogy with linear motion, we define:

$$\text{average angular velocity} \equiv \frac{\Delta\theta}{\Delta t}$$

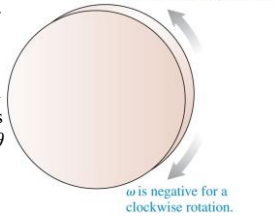
- As the time interval Δt becomes very small, we arrive at the definition of instantaneous **angular velocity**

$$\omega \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta\theta}{\Delta t} = \frac{d\theta}{dt} \quad (\text{angular velocity})$$



Angular Velocity

- Angular velocity ω is the *rate* at which a particle's angular position is changing
- As shown in the figure, ω can be positive or negative, and this follows from our definition of θ
- A particle moves with uniform circular motion if ω is constant
- ω and θ are related graphically:



$\omega =$ slope of the θ -versus- t graph at time t
 $\theta_t = \theta_i +$ area under the ω -versus- t curve between t_i and t_f
 $= \theta_i + \omega \Delta t$

Angular Velocity in Uniform Circular Motion

- When angular velocity ω is constant, this is uniform circular motion
- In this case, as the particle goes around a circle one time, its angular displacement is $\Delta\theta = 2\pi$ during one period $\Delta t = T$
- The absolute value of the constant angular velocity is related to the period of the motion by

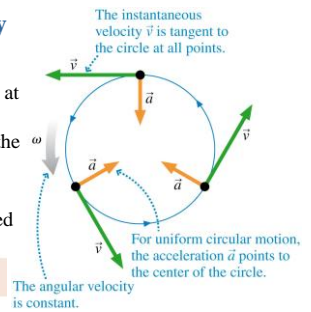
$$|\omega| = \frac{2\pi \text{ rad}}{T} \quad \text{or} \quad T = \frac{2\pi \text{ rad}}{|\omega|}$$

Section 4.6

Tangential Velocity

- The tangential velocity component v_t is the rate ds/dt at which the particle moves around the circle, where s is the arc length
- The tangential velocity and the angular velocity are related by

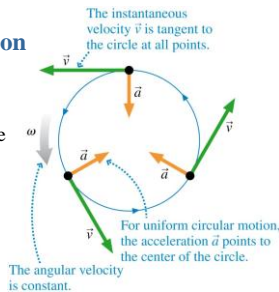
$$v_t = \omega r \quad (\text{with } \omega \text{ in rad/s})$$



- In this equation, the units of v_t are m/s, the units of ω are rad/s, and the units of r are m

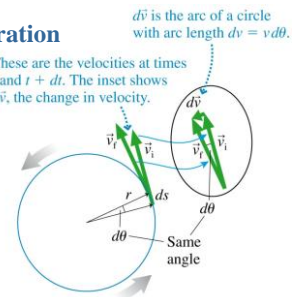
Centripetal Acceleration

- In uniform circular motion, although the speed is constant, there is an acceleration because the *direction* of the velocity vector is always changing
- The acceleration of uniform circular motion is called **centripetal acceleration**
- The direction of the centripetal acceleration is toward the center of the circle
- The magnitude of the centripetal acceleration is constant for uniform circular motion



Centripetal Acceleration

- The figure shows the velocity \vec{v}_i at one instant and the velocity \vec{v}_f an infinitesimal amount of time dt later
- By definition, $\vec{a} = d\vec{v}/dt$
- By analyzing the isosceles triangle of velocity vectors, we can show that:

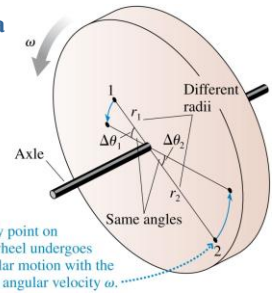


$$\vec{a} = \left(\frac{v^2}{r}, \text{toward center of circle} \right) \quad (\text{centripetal acceleration})$$

which can be written in terms of angular velocity as: $a = \omega^2 r$

Section 4.7

Angular Velocity of a Rotating Object



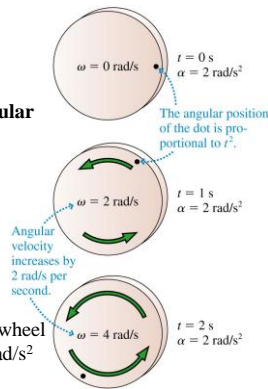
- The figure shows a wheel rotating on an axle
- Points 1 and 2 turn through the *same angle* as the wheel rotates
- That is, $\Delta\theta_1 = \Delta\theta_2$ during some time interval Δt
- Therefore $\omega_1 = \omega_2 = \omega$
- All points on the wheel rotate with the same angular velocity
- We can refer to ω as the angular velocity of the wheel

Angular Acceleration

- Suppose a wheel's rotation is speeding up or slowing down
- This is called **nonuniform circular motion**
- We can define the *angular acceleration* as

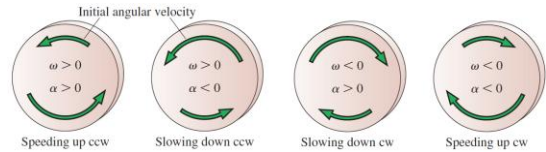
$$\alpha \equiv \frac{d\omega}{dt} \quad (\text{angular acceleration})$$

- The units of α are rad/s^2
- The figure to the right shows a wheel with angular acceleration $\alpha = 2 \text{ rad/s}^2$



The Sign of Angular Acceleration

- If ω is counter-clockwise and $|\omega|$ is increasing, then α is positive
- If ω is counter-clockwise and $|\omega|$ is decreasing, then α is negative
- If ω is clockwise and $|\omega|$ is decreasing, then α is positive
- If ω is clockwise and $|\omega|$ is increasing, then α is negative



Angular Kinematics

- The same relations that hold for linear motion between a_x , v_x and x apply analogously to rotational motion for α , ω and θ
- There is a graphical relationship between α and ω :

α = slope of the ω -versus- t graph at time t

$\omega_t = \omega_i + \text{area under the } \alpha\text{-versus-}t \text{ curve between } t_i \text{ and } t_f$

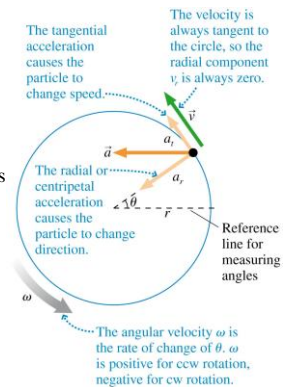
- The table shows a comparison of the rotational and linear kinematics equations for constant α or constant a_s :

Rotational kinematics	Linear kinematics
$\omega_f = \omega_i + \alpha \Delta t$	$v_{fx} = v_{ix} + a_s \Delta t$
$\theta_f = \theta_i + \omega_i \Delta t + \frac{1}{2} \alpha (\Delta t)^2$	$s_f = s_i + v_{ix} \Delta t + \frac{1}{2} a_s (\Delta t)^2$
$\omega_f^2 = \omega_i^2 + 2\alpha \Delta\theta$	$v_{fx}^2 = v_{ix}^2 + 2a_s \Delta s$

Acceleration in Nonuniform Circular Motion

- The particle in the figure is moving along a circle and is speeding up
- The centripetal acceleration is $a_r = v_t^2/r$, where v_t is the tangential speed
- There is also a tangential acceleration a_t which is always tangent to the circle
- The magnitude of the total acceleration is

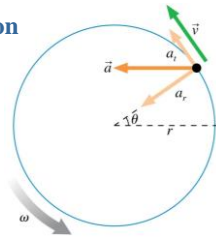
$$a = \sqrt{a_r^2 + a_t^2}$$



Nonuniform Circular Motion

- A particle moves along a circle and may be changing speed
- The *distance traveled* along the circle is related to θ :

$$s = r\theta \quad (\text{with } \theta \text{ in rad})$$



- The *tangential velocity* is related to the angular velocity:

$$v_t = \omega r \quad (\text{with } \omega \text{ in rad/s})$$

- The *tangential acceleration* is related to the angular acceleration:

$$a_t = \frac{dv_t}{dt} = \frac{d(\omega r)}{dt} = \frac{d\omega}{dt} r = \alpha r$$