

# Torsion Pendulum Experiment

This document introduces the Torsion Pendulum experiment from the Physics laboratory at the University of Toronto. It is intended to be used before you begin the experiment. The *Preparatory Questions* at the end of this document should be answered and turned in to your Demonstrator before you begin to work on the experiment.

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## Requirements

In order to effectively use this page, your browser needs to be capable of viewing *Flash* animations, also known as *swf* files. The Flash player is available free from <http://www.macromedia.com/>. The animation is for Version 5 of the player or later.

A summary of this page are also available below. It is in *pdf* format. Accessing this document will require that you have the *Acrobat Reader*, which is available free from <http://www.adobe.com>.

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## Introduction

**Simple Harmonic Motion**

The diagram shows three examples of simple harmonic motion. On the left, a blue spring is attached to a black horizontal bar, with a grey mass hanging from it. A vertical double-headed arrow labeled  $y$  indicates the displacement from the equilibrium position. In the center, a green vertical line represents displacement from equilibrium, with a red dot at the bottom and a red  $y$  label at the top. On the right, a grey hollow cylinder is suspended from a black horizontal bar by a blue wire. A curved arrow labeled  $\theta$  indicates the angular displacement from the equilibrium position.

**Example 1: Linear**

**Example 2: Rotational**

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In the above animation, we see two examples of *Simple Harmonic Motion*. On the left a mass hanging from a spring is oscillating vertically; we call its vertical displacement from its equilibrium position  $y$ . On the right a hollow cylinder hanging from a wire is oscillating in the horizontal plane; we call its angular displacement from its equilibrium position  $\theta$ . As the slider in the center shows, although the systems are quite different their displacements as a function of time are identical.

The system represented by the animation to the right is called a *Torsion Pendulum*, and will be the subject of this

experiment.

If the displacement from equilibrium is  $r$ , then the displacement as a function of time  $t$  for both these examples is:

$$r(t) = r_0 \sin(\omega t + \phi) \tag{1}$$

where:

$r_0$  = the maximum amplitude

$\omega \equiv$  the *angular frequency* =  $2 \pi / T$

$T$  = the *period* of the oscillation

$\phi$  = the *phase angle*

For the spring-mass system above, we used the symbol  $\mathbf{y}$  in the animation in place of  $\mathbf{r}$ . For the Torsion Pendulum, we used  $\theta$  in place of  $\mathbf{r}$ . The point is that except for the symbols used, the mathematical description of these two systems are identical.

The similarity of the mathematical description of these two systems goes deeper than just Equation 1.

Spring-Mass System	Torsion Pendulum
<p>The force <math>F</math> exerted by the spring on the mass is proportional to the displacement <math>x</math> of the mass from the equilibrium position:</p> $F = -k x$ <p>where <math>k</math> is a constant for a given massless spring.</p>	<p>The torque <math>\tau</math> exerted by the wire on the cylinder is proportional to the displacement <math>\theta</math> of the cylinder from the equilibrium position:</p> $\tau = -\kappa \theta$ <p>where <math>\kappa</math> is a constant for a given massless wire. <math>\kappa</math> is called the <i>torsion constant</i>.</p>
<p>The period <math>T</math> of the oscillation is given by:</p> $T = 2 \pi \sqrt{\frac{m}{k}}$ <p>where <math>m</math> is the mass of the object hanging from the spring.</p>	<p>The period <math>T</math> of the oscillation is given by:</p> $T = 2 \pi \sqrt{\frac{I}{\kappa}}$ <p>where <math>I</math> is the <i>moment of inertia</i> of the object hanging from the wire.</p>

Thus the moment of inertia  $I$  for the Torsion Pendulum has the same role as the mass  $m$  for the spring-mass system.

The period of oscillation for a rotating object, the equation in the lower right of the above table, is:

$$T = 2 \pi \sqrt{\frac{I}{\kappa}}$$

This can be re-written as:

$$T^2 = \left[ \frac{4\pi^2}{\kappa} \right] I \quad (2)$$

In the experiment you will measure the period  $T$  for a number of objects with different moments of inertia  $I$ . Then a plot of  $T^2$  versus  $I$  should be a straight line with slope  $4\pi^2/\kappa$ . Thus, you may determine  $\kappa$  for the wire.

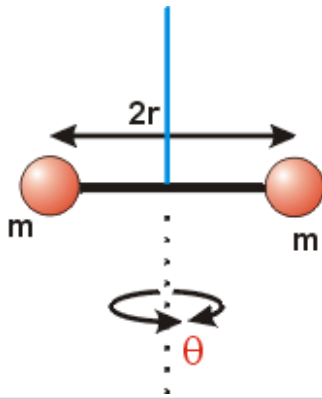
The fact that the period of oscillation of a torsion pendulum is constant for a given moment of inertia and wire is used to build clocks. The clock to the right is a beautiful example.

This clock was built in 1880. The photograph is by *The Old Father Time Clock Centre*, and is used by permission. The original is at <http://www.oldfathertime.net/torsion/torsion.html>.



The moment of inertia is a function not only of the mass of the object hanging from the wire but also of how that mass is distributed about the axis of rotation. Some examples are:

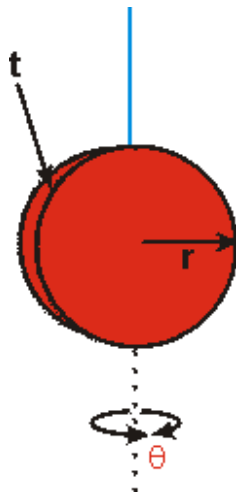
**Example 1:** Two point masses  $m$  each a distance  $r$  from the axis of oscillation, connected by a massless rod.



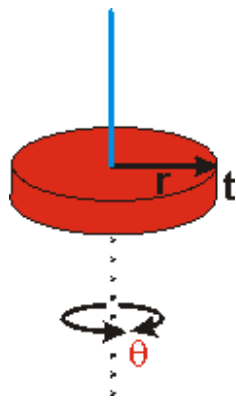
$$I = 2 [m r^2]$$

**Example 2:** A disc of mass  $M$ , radius  $r$  and thickness  $t$  oscillating around the diameter that goes through the center of mass.

$$I = M \left( \frac{r^2}{4} + \frac{t^2}{12} \right)$$

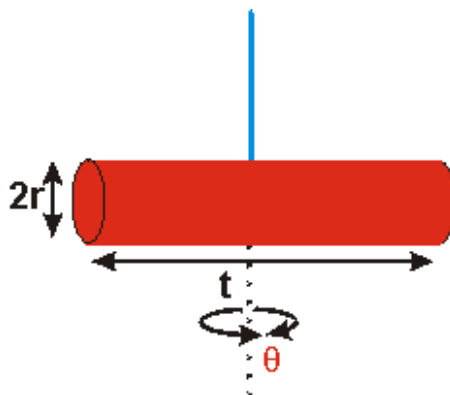


**Example 3:** The same disc as before, but oscillating around the perpendicular to its face through the center.



$$I = \frac{Mr^2}{2}$$

**Example 4:** A cylinder of mass  $M$ , radius  $r$  and length  $t$ .

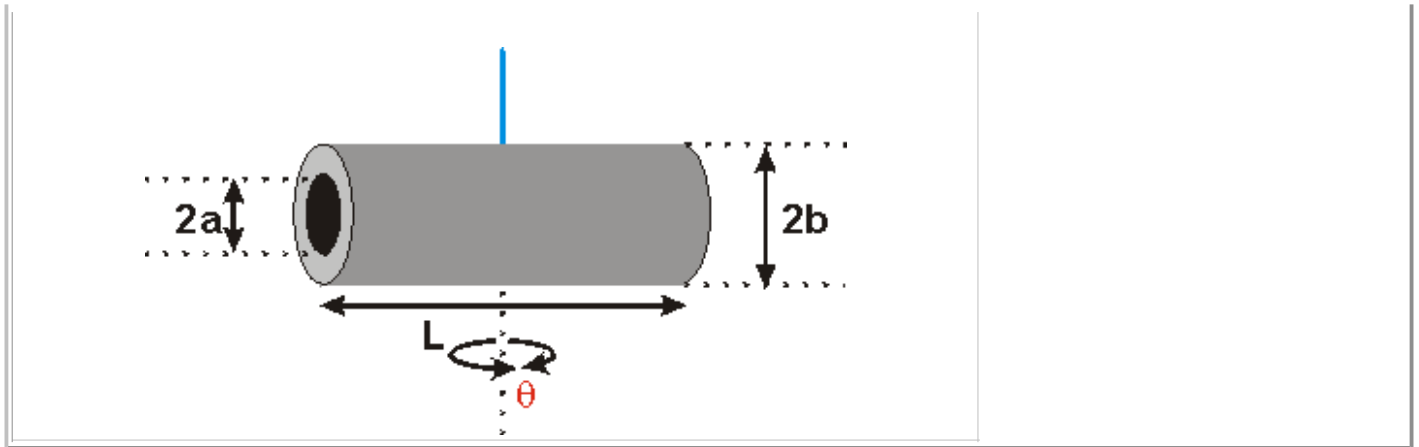


$$I = M \left( \frac{r^2}{4} + \frac{t^2}{12} \right)$$

Note: this is the same result as Example 2 above.

**Example 5:** A hollow cylinder of mass  $M$ , length  $L$ , inner radius  $a$  and outer radius  $b$ .

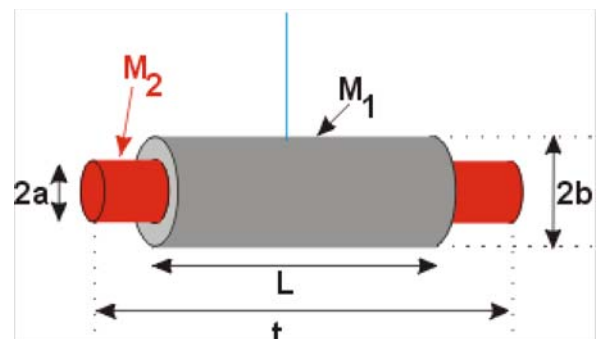
$$I = M \left[ \frac{L^2}{12} + \frac{a^2 + b^2}{4} \right]$$



Deriving these examples requires knowing that the moment of inertia of a differential mass  $d\mathbf{m}$  rotating at a distance  $\mathbf{r}$  from the axis of rotation has a differential moment of inertia  $d\mathbf{I} = \mathbf{r}^2 d\mathbf{m}$ . Then one integrates all the differential masses over the entire body to calculate the total moment of inertia. This sort of mathematical manipulation, which is an example of *theoretical physics*, is not part of this experiment, which is teaching *experimental physics*.

To the right we show the cylinders from Examples 4 and 5 combined into a single complex object. The total moment of inertia is just the sum of those two examples:

$$I = M_1 \left[ \frac{L^2}{12} + \frac{a^2 + b^2}{4} \right] + M_2 \left( \frac{a^2}{4} + \frac{t^2}{12} \right)$$




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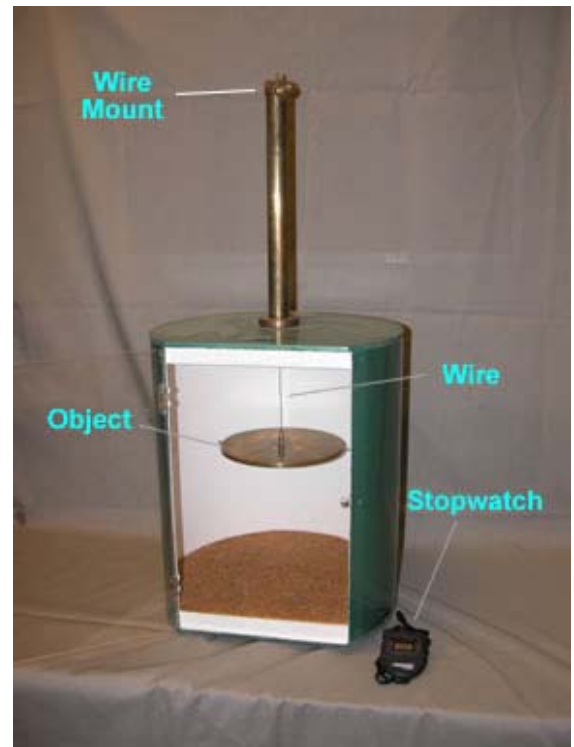
## The Apparatus

The photograph to the right shows the apparatus for the experiment.

The *wire* is mounted at the top, and hangs down into the chamber. We show a brass disc hanging from the wire. Its orientation is the same as **Example 3** in the *Introduction*.

You will measure different objects' period of oscillation with the supplied stopwatch.

Barely visible in the photograph is a plexiglas door, which is open in the picture. You will close it before taking data so that air currents do not disturb the motion of the object.



Do **not** attempt to adjust the wire with the mount at the top. If you suspect the apparatus needs adjustment see your Demonstrator or one of the lab technologists.



You will measure the period of oscillation for 4 different moments of inertia. The above photograph shows the brass disc oriented for one of the moments of inertia you will measure. Here are the other 3 moments you will use:

<p>The disc hanging from the wire in another orientation. This corresponds to <b>Example 2</b> above.</p>	<p>A hollow cylinder. Its moment of inertia is given by <b>Example 5</b>.</p>	<p>The same hollow cylinder and a solid brass rod. This corresponds to <b>Examples 4 and 5</b>, whose moment of inertia is given above.</p>

## Data Collection & Analysis

You will determine the moments of inertia by directly measuring the mass and dimensions of the object. You should use the most appropriate instrument to measure each dimension. Possible instruments include a meter stick, a vernier caliper, and a micrometer.

A document on reading a vernier is available by clicking on the red button to the right. It will appear in a separate window, and has a file size of 56k. You should have your browser enabled for *Java* to effectively use this introduction.



A document on using a micrometer is available by clicking on the blue button to the right. It will appear in a separate window, and has a file size of 86k.



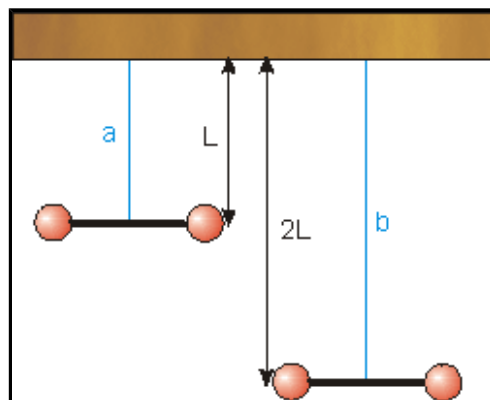
You will measure the period of oscillation for each moment of inertia with the stopwatch. A preparatory question below explores the best procedure to use for this measurement.

Although the data collection is simple and straightforward, the analysis of your results and especially the calculation of the uncertainties in your determinations of the moments of inertia may seem at first to be a bit daunting. A preparatory question below, however, is intended to show you how to make these calculations much simpler than they seem.

## Preparatory Questions

We hope that the following questions will guide you in your preparation for the experiment you are about to perform. They are not meant to be particularly testing, nor do they contain any "tricks". Once you have answered them, you should be in a good position to begin the experiment.

- You are doing your laundry. In order to answer the following questions you will need to make some rough estimates of the weight of your wet laundry and the size of the laundry tub in the washing machine.
  - Estimate the moment of inertia of your clothes when the washing machine is in its *spin cycle*.
  - Estimate the uncertainty in your determination of the the moment of inertia of your clothes.
  - Does the moment of inertia change of your clothes change from the beginning to the end of the cycle? Why? By how much?



Two torsion pendulums are constructed of identical wires except that one wire is twice as long as the other, as shown. The objects hanging from the wires have identical moments of inertia. What is the ratio of the period of oscillation of the two objects:

$$T_a / T_b$$

- In the **Introduction**, some examples of moments of inertia  $I$  were given. Consider the moment of inertia of the hollow cylinder of Example 5 as being that of a solid cylinder of radius  $b$  minus that of a solid cylinder of radius  $a$ , with both cylinders having the same length  $t$ . Use the result of Example 4 to derive the result of Example 5. You will wish to use the fact that the mass  $M$  of a solid cylinder is:

$$M = \rho \pi r^2 t$$

where  $\rho$  is its density,  $r$  its radius and  $t$  its length

4. In the experiment you will be measuring the period of oscillation  $T$  of a number of objects. One procedure would be to measure the time for 20 oscillations,  $t_{20}$ , and repeat the measurement 5 times. Another procedure would be to measure the time for 5 oscillations,  $t_5$ , and repeat the measurement 20 times. Assume, reasonably, that the error in the determination of the time for 20 oscillations is the same as the error in the determination of the time for 5 oscillations. Calculate the error in the period for both procedures to determine which will give the smallest error in the value of the period. If you have studied the modules on Error Analysis at <http://www.upscale.utoronto.ca/PVB/Harrison/ErrorAnalysis/> this question may be familiar.
5. You are measuring the moment of inertia of a hollow cylinder, as in **Example 5** above. Here are the values:

$L$	$11.72 \pm 0.02$ cm	Measured with a meter stick
$2a$	$15.4 \pm 0.3$ mm	Measured with a vernier caliper
$2b$	$34.2 \pm 0.3$ mm	Measured with a vernier caliper
$M$	$1289.38 \pm 0.04$ g	Measured with a balance

- Convert all the above values to SI units.
- What is the percentage error in  $L$ ?
- What is the value and error in  $p = L^2/12$ ?
- What is the percentage error in  $p$ ? How does it compare to the percentage error in  $L$ ?
- What is the value, error, and percentage error in  $a$ ?
- What is the value and error in  $a^2$ ?
- How does the percentage error in  $a^2$  compare to the percentage error in  $a$ ?
- What is the value and error in  $b^2$ ?
- What is the value and error in  $q = (a^2 + b^2)/4$ ?
- For the previous calculation, is one of the errors negligible? If yes, which?
- What is the percentage error in  $q$ ? Have you calculated any other percentage errors with this value?
- What is the value and error in  $r = p + q$ ?
- For the previous calculation, is one of the errors negligible? If yes, which?
- What is the value and error in the moment of inertia  $I = M r$ ?
- For the previous calculation, is one of the errors negligible? If yes, which?
- What is the percentage error in  $I$ ? Have you calculated any other percentage errors with this value?

Note that the above numbers are fictitious. However, the principles of error propagation and in particular the identification of negligible errors will be used in your analysis. Negligible errors do not even have to be accounted for in real calculations. Thus, by paying attention to the values before pounding numbers into your calculator, you can save much time and effort.

## Summary

As promised, we have prepared a summary of the information presented above. It does not attempt to provide a full discussion, but just reviews the "high points" from above.

You may access the summary by clicking on the green button to the right. The summary is in pdf format, will appear in separate window, and has a file size of 47k. You may wish to print this document.





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## Authors

The photograph of the pendulum clock is Copyright © The Old Father Time Clock Centre 1999-2002, and is used by permission.

All other parts of this document, including all figures, animations and the video, was written by David M. Harrison, Dept. of Physics, Univ. of Toronto, [harrison@physics.utoronto.ca](mailto:harrison@physics.utoronto.ca) in October/November 2002.

Earlier versions of the Guide Sheet were written or revised by Macolm Graham, David M. Harrison, Tony Key, Joe Vise, and others.

This is \$Revision: 0.3 \$, \$Date: 2003/08/07 12:55:00 \$ (y/m/d UTC).