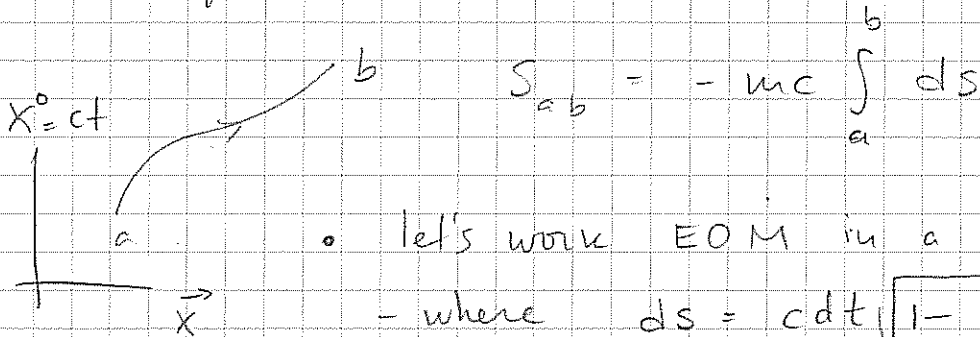


As usual S is useful to

- (a) find EOM
- (b) find conserved quantities (symmetries \rightarrow \rightarrow conserv. laws)

(a) get EOM ---



- let's work EOM in a given inertial frame - where $ds = c dt \sqrt{1 - \vec{v}^2/c^2}$

- we'll try to write answer in 4-vector notation - and if we can, this means these EOMs are true in any frame

So $S_{ab}[\vec{x}] = -mc \int_{t_a}^{t_b} dt \sqrt{1 - \left(\frac{d\vec{x}}{dt}\right)^2} \frac{1}{c^2}$

every time-like trajectory is specified by giving $\vec{x}(t)$

this is action evaluated on trajectory $\vec{x}(t)$

need $\delta S = S[\vec{x} + \delta\vec{x}] - S[\vec{x}]$ (to linear order in $\delta\vec{x}$) = 0

this is just like any old nonrelativistic problem, except +

$$L(\vec{x}, \dot{\vec{x}}, t) = -mc \sqrt{1 - \left(\frac{d\vec{x}}{dt}\right)^2} \frac{1}{c^2}$$

we know EOMs are

$$\frac{\partial L}{\partial \dot{\vec{x}}} = \frac{d}{dt} \frac{\partial L}{\partial \ddot{\vec{x}}}$$

$$0 = \frac{d}{dt} \frac{\partial}{\partial \ddot{\vec{x}}} \left(-mc \sqrt{1 - \frac{\dot{\vec{x}}^2}{c^2}} \right)$$

So EOM is:

$$\frac{d}{dt} \frac{d}{d\dot{\vec{x}}} \sqrt{1 - \frac{\dot{\vec{x}}^2}{c^2}} = 0$$

$$\frac{d}{dt} \left(\frac{\dot{\vec{x}}/c}{\sqrt{1 - \dot{\vec{x}}^2/c^2}} \right) = 0$$

$$\frac{d}{dt} (\gamma \vec{v}) = 0$$

$$\frac{d}{dt} (u^{1,2,3}) = 0$$

$$\text{since } u^i = (\gamma, \gamma \vec{v})$$

Now this is NOT

YET a 4-vector

equation — but it implies one w/ some work:

$$0 = \frac{d}{dt} (\gamma \vec{v}) = \frac{d}{dt} \left[\left(1 - \frac{v^2}{c^2}\right)^{-1/2} \vec{v} \right] = \left(1 - \frac{v^2}{c^2}\right)^{-1/2} \left[\dot{\vec{v}} + \frac{\vec{v} (\vec{v} \cdot \dot{\vec{v}})}{c^2 - v^2} \right] = 0$$

Clearly $\dot{\vec{v}} = 0$ is a solution $\Rightarrow \vec{v} = \text{const} \Rightarrow \vec{x} = \vec{v}t + \vec{x}_0$

But is there a solution w/ $\dot{\vec{v}} \neq 0$? \rightarrow Claim: NO: if $\dot{\vec{v}} \neq 0$ then

$$\text{use } \dot{\vec{v}} + \frac{\vec{v} (\vec{v} \cdot \dot{\vec{v}})}{c^2 - v^2} = 0, \times \vec{v} \Rightarrow \vec{v} \cdot \dot{\vec{v}} + \frac{v^2}{c^2 - v^2} \vec{v} \cdot \dot{\vec{v}} = 0 \Rightarrow$$

$$\Rightarrow \vec{v} \cdot \dot{\vec{v}} \frac{c^2}{c^2 - v^2} = 0 \Rightarrow \vec{v} \cdot \dot{\vec{v}} = 0 \Rightarrow \text{but then } \dot{\vec{v}} = 0 \text{ — contradiction!}$$

So then $\frac{d}{dt} \gamma \vec{v} = 0 \rightarrow \vec{v} = \text{const} \rightarrow$

(54)

$\Rightarrow \frac{d}{dt} \gamma = 0$

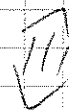
but then also $\frac{du^0}{dt} = 0$ since $u^0 = \gamma$

so we have $\frac{du^i}{dt} = 0$ -- this is almost

a 4-vector relation $\rightarrow x$ by $\frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$ (never 0 or ∞)

$\frac{d u^i}{\sqrt{1 - \frac{v^2}{c^2}} dt} = 0 \rightarrow \frac{d u^i}{ds} = 0$

"4 acceleration = 0"



4 vector EOM

Similarly we can find conserved quantities!

Symmetries: $t \rightarrow t + \text{const}$
 $\vec{x} \rightarrow \vec{x} + \text{const}$

homogeneity of spacetime

$x^i \rightarrow x^i + \text{const}$

Again use

$$L = -mc \sqrt{1 - \frac{v^2}{c^2}}$$

"generalized momentum"

homogeneity of space $\rightarrow \frac{d}{dt} \frac{\partial L}{\partial \vec{v}} = 0$

by what we already did (- used EOM)

$$\frac{d}{dt} (mc \gamma \vec{v}) = 0$$

$$\frac{d}{dt} (mc \gamma v^i) = 0$$

$$\frac{d}{dt} (mc \gamma v^i) = 0$$

$$\frac{d}{ds} (mc u^i) = 0$$

4 momenta conservation

$$p^i = mc u^i = (\gamma mc, \gamma m \frac{\vec{v}}{c}) = (\gamma mc, \gamma m \vec{v})$$

Recall for $L = L(q, \dot{q}, t)$

$$\frac{d}{dt} L = \frac{\partial L}{\partial q} \dot{q} + \frac{\partial L}{\partial \dot{q}} \ddot{q} + \frac{\partial L}{\partial t}$$

→ assume no explicit t-dep.

$$= \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \dot{q} + \frac{\partial L}{\partial \dot{q}} \ddot{q}$$

$$= \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \dot{q} \right) - L = 0$$

conserved quantity $\equiv E$ - energy

For our $L = -mc^2 \sqrt{1 - \frac{\vec{v}^2}{c^2}}$

$$\begin{aligned}
 E &= \vec{v} \cdot \frac{\partial L}{\partial \vec{v}} - L = \\
 &= \vec{v} (-mc^2) \frac{1}{2\sqrt{1 - \frac{\vec{v}^2}{c^2}}} \left(-2 \frac{\vec{v}}{c^2} \right) + mc^2 \sqrt{1 - \frac{\vec{v}^2}{c^2}} \\
 &= \frac{m \vec{v}^2}{\sqrt{1 - \frac{\vec{v}^2}{c^2}}} + mc^2 \sqrt{1 - \frac{\vec{v}^2}{c^2}} = \\
 &= \frac{m \vec{v}^2 + mc^2 (1 - \frac{\vec{v}^2}{c^2})}{\sqrt{1 - \frac{\vec{v}^2}{c^2}}} = \frac{mc^2}{\sqrt{1 - \frac{\vec{v}^2}{c^2}}}
 \end{aligned}$$

So energy is $E = \gamma mc^2$

$$\frac{d}{dt} E = 0$$

$$\nabla \frac{d}{dt} (m c u^i) = 0$$

for free particle.

four-momentum

$$p^i = m c u^i \quad \text{conservation}$$

$$p^i = (p^0, \vec{p}), \quad p^0 = \gamma m c = \frac{E}{c}, \quad p^i p_i = m^2 c^2$$

$$\vec{p} = \gamma m \vec{v} = \frac{E \vec{v}}{c^2}$$

Notice: as $\vec{v} \rightarrow 0$ $E \rightarrow mc^2$ = "rest energy"

(necessary consequence of relativity) \leftarrow