PHY131H1F - Hour 23





Today:

- 8.1 Extended and Rigid Bodies
- 8.2 Torque (rhymes with "fork")

Mastering Physics

What's up on the MyLab and Mastering?

- Notice that Homework 8 has been posted on MasteringPhysics. It is due Friday Nov.16, which is after Reading Week.
- Also, I have posted an optional item called "Ch.8 Videos Optional" which I recommend you check out.

Mastering Physics

Chapter 8 Videos (Optional)

• Return of "Buzzcut Guy"! Woot!

- Including, Buzzcut Guy walks the plank!
- And two Khan-Academy-style videos about solving Ch.8 problems.





Second Midterm

• The second midterm will cover chapters 5, 6 and 7 (and we expect you to still remember stuff from chapters 2-4):

Tuesday Nov. 13th, from 6:10pm - 7:30pm.

- The room you go to is based on the first letters of your last name:
 - A LOCH = EX200
 - LOKE ZU = EX100
- If you have a course conflict you will be permitted to register to write at the alternative sitting on Tuesday Nov. 13th, from 4:40pm - 6:00pm (in a room TBA).
- If you already registered for the first midterm for the alternate sitting, you do
 not need to re-register for the second midterm; you are automatically in the
 alternative sitting for the second midterm.

- Rolling is a combination of linear and circular motion.
- Determine the speed of the points A, B, and C with respect to the ground for the bicycle that is moving at a constant speed of 4 m/s.
- Determine the speed of the points A, B, and C with respect to the bicycle, assuming the bicycle is moving at a constant speed of 4 m/s.

Ch.5 Review: Rolling without skidding

S frame: the ground

 $\vec{V} = v, \text{ to the right}$

The wheel rotates counterclockwise (CCW).

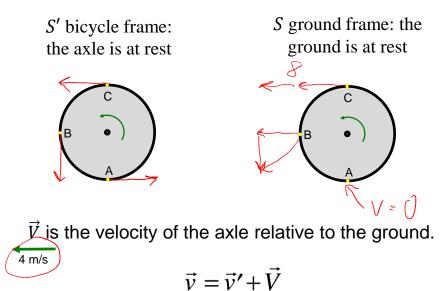
The tangential speed of a point on the rim is v = 4 m/s, relative to the axle.

In "rolling without skidding", the axle moves at speed v. This is the S' frame.



Key Content State
Key Content State

Problem 5.11



Ch.5 Review: Rolling without skidding

 Determine the speed of the points A, B, and C with respect to the bicycle, assuming the bicycle is moving at a constant speed of 4 m/s. Rotation only:

> C: 4 m/s to the left. B: 0 + 4 m/s to the left = 0 m/s. A: 4 m/s to the right.

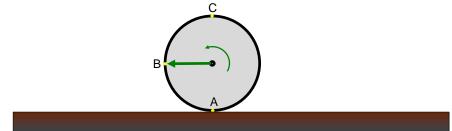
 Determine the speed of the points A, B, and C with respect to the ground for the bicycle that is moving at a constant speed of 4 m/s. Add linear motion:

C: 4 m/s to the left + 4 m/s to the left = 8 m/s to the left. B: 0 + 4 m/s to the left = 4 m/s to the left. A: 4 m/s to the right + 4 m/s to the left = 0 m/s



Homework 5

Problem 5.11



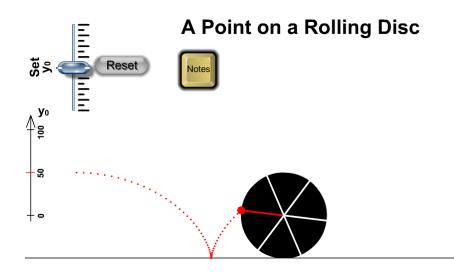
• In "rolling without skidding", point A, which is touching the ground, has a momentary velocity of **zero!**

• That means, if your car is accelerating or decelerating or turning, it is *static friction* of the road on the wheels that provides the net force which accelerates the car

[Animation]

Animation of Rolling Without Skidding

https://faraday.physics.utoronto.ca/GeneralInterest/Harrison/Flash/ClassMechanics/RollingDisc/RollingDisc.html





No matter what the speed, four points on this car are always *at rest!*Which points? The bottoms of the four tires!

- A wheel rolls much like the treads of a tank.
- The bottom of the wheel is *at rest* relative to the ground as it rolls.

Ch.5 Review: Learning Catalytics Question (part 1 of 2)

You are sitting in your car, and you step on the gas pedal. The car accelerates forward.

Since the car has a large forward acceleration, there must be a large forward force acting on the car, $\vec{F}_{1 on 2}$.

Here, object 2 is the car.

What is object 1?



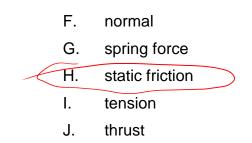
- B. The engine
- C. The air
- D. The gas pedal
- E. An invisible string attached to the front of the car

Ch.5 Review: Learning Catalytics Question (part 2 of 2)

You are sitting in your **C**ar, and you step on the gas pedal. The car accelerates forward, due to the large forward force from the **E**arth, $\vec{F}_{E \text{ on } C}$

What kind of force is $\vec{F}_{E on C}$?

- A. air resistance
- B. applied force
- C. electric
- D. kinetic friction
- E. magnetic

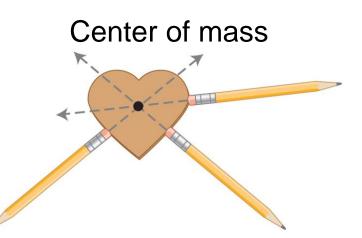


What's the Big Idea of Chapters 8 and 9?

- So far we've kind of been neglecting the fact that objects have size and shape.
- This has been the "point particle" approximation.
- For this chapter we will start thinking about "extended bodies", which just means objects that are not points, but have some shape and size.
- Force, momentum and energy are still important, but there are some new things, like:
 - Torque: kind of like force (with different units), but it's what get's objects turning.
 - Rotation: things can spin or roll!



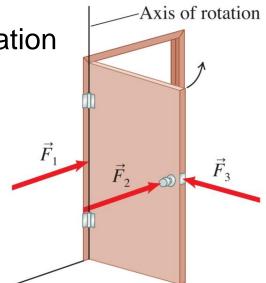
- A rigid body is a model for an extended object.
- We assume that the object has a nonzero size but the distances between all parts of the object remain the same (the size and shape of the object do not change).



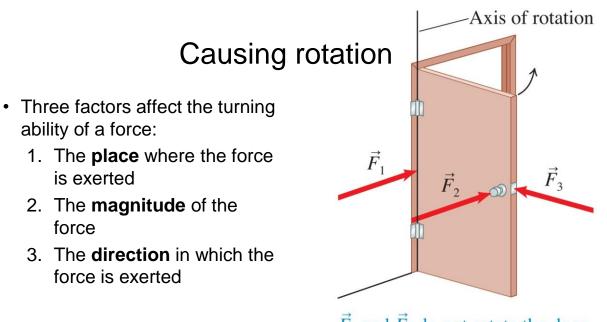
- A rigid body possesses a special point such that if a force is exerted on that point, the object will not turn.
- We call this point the object's center of mass.

Axis of rotation

- When objects turn around an axis, physicists say that they undergo **rotational** motion.
- We call the imaginary line passing through the hinges the **axis of rotation**.

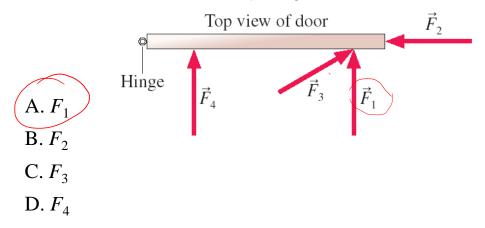


 \vec{F}_1 and \vec{F}_3 do not rotate the door, whereas \vec{F}_2 moves it easily.



 \vec{F}_1 and \vec{F}_3 do not rotate the door, whereas \vec{F}_2 moves it easily.

Consider the common experience of pushing open a door. Shown is a top view of a door hinged on the left. Four pushing forces are shown, all of equal strength. Which of these will be most effective at opening the door?





Torque τ **produced by a force** The torque produced by a force exerted on a rigid body about a chosen axis of rotation is

$$\tau = \pm Fl\sin\theta$$

where F is the magnitude of the force, l is the magnitude of the distance between the point where the force is exerted on the object and the axis of rotation, and θ is the angle that the force makes relative to a line connecting the axis of rotation to the point where the force is exerted

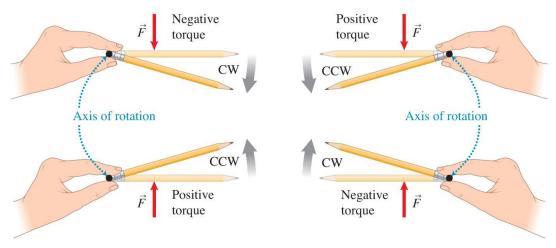
• The SI unit of force is the Newton-meter (N-m).

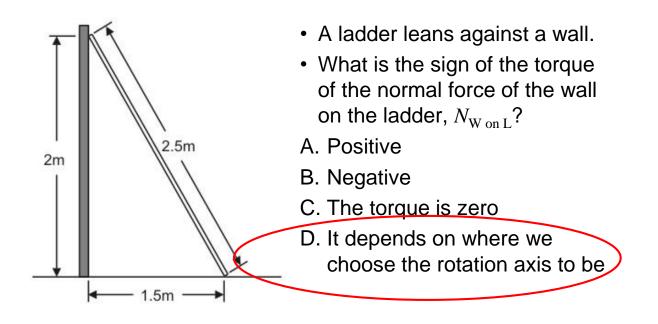
[Doc Cam example]

Ch.8 Example. Luis uses a 20 cm long wrench to turn a nut. The wrench handle is tilted 30° above the horizontal, and Luis pulls straight down on the end with a force of 100 N. Calculate the torque Luis exerts on the nut? - wrench Sketch and translate norm = 100 N 30° rotation axis Nut 0 = angle between $0 = 40 - 30 = 60^{\circ}$ \overrightarrow{F} direction and line connecting rotation axis and Simplify and diagram epresent mathematically point where force $T = \pm FL \sin \theta$ clockwise \Rightarrow negative T. Represent mathematically Solve and Evaluate $T = -(100 \text{ N})(0.20 \text{ m}) \sin 60^{\circ}$ $T = -17.3 \text{ N} \cdot \text{m} = \text{I} \text{ don't know}$ how to evaluate treques.²

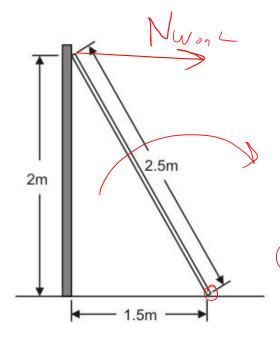
Sign Convention for Torque (historical)

- If the torque tends to produce a counterclockwise rotation, this is positive torque.
- If the torque tends to produce clockwise rotation, this is negative torque.





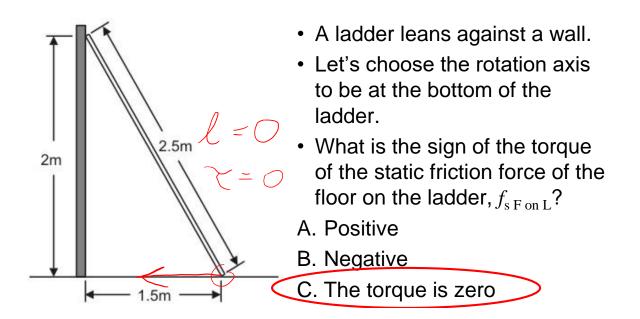
Learning Catalytics Question



- A ladder leans against a wall.
- Let's choose the rotation axis to be at the bottom of the ladder.
- What is the sign of the torque of the normal force of the wall on the ladder, $N_{\rm W \, on \, L}$?
- A. Positive

B. Negative

C. The torque is zero

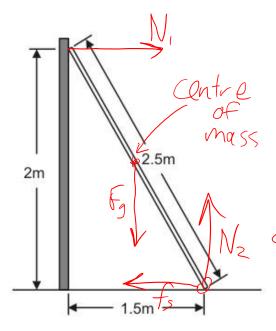


The heart does not tip if supported under its center of mass.

Center of mass.

Where is the gravitational force exerted on a rigid body?

- When calculating the torque due to gravity, you may treat the object as if all its mass were concentrated at the centre of mass.
- That is why the object's center of mass is sometimes called the object's **centre of gravity**.



- A <u>uniform ladde</u>r leans against a wall.
- Let's choose the rotation axis to be at the bottom of the ladder.
 - What is the sign of the torque of the force of gravity of the Earth on the ladder, F_{g E on L}?
 A Positive
 - B. Negative
 - C. The torque is zero

Reading Week

- Nov. 5 9 is the "Fall Reading Week" No Classes!
- So, I'll see you on Monday Nov. 12! We'll continue with Static Equilibrium problems from Chapter 8.
- And don't forget there's a test on Tue. Nov.13!
- Until then... have a great break!

