

## PHY131H1F - Hour 23



This is a torque wrench.



### Today:

8.1 Extended and Rigid Bodies

8.2 Torque (rhymes with "fork")

### Mastering Physics

## What's up on the MyLab and Mastering?

- Notice that Homework 8 has been posted on MasteringPhysics. It is due Friday Nov.16, which is after Reading Week.
- Also, I have posted an optional item called "Ch.8 Videos – Optional" which I recommend you check out.

## Chapter 8 Videos (Optional)

- Return of “Buzzcut Guy”! Woot!
- Including, Buzzcut Guy walks the plank!
- And two Khan-Academy-style videos about solving Ch.8 problems.



## Second Midterm

- The second midterm will cover chapters 5, 6 and 7 (and we expect you to still remember stuff from chapters 2-4):

Tuesday Nov. 13<sup>th</sup>, from 6:10pm - 7:30pm.

- The room you go to is based on the first letters of your last name:
  - A - LOCH = EX200
  - LOKE - ZU = EX100
- If you have a course conflict you will be permitted to register to write at the alternative sitting on Tuesday Nov. 13<sup>th</sup>, from 4:40pm - 6:00pm (in a room TBA).
- If you already registered for the first midterm for the alternate sitting, you do not need to re-register for the second midterm; you are automatically in the alternative sitting for the second midterm.

# Ch.5 Review: Rolling without skidding

← Homework 5

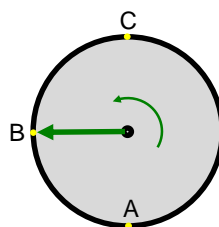
## Problem 5.11

- Rolling is a combination of linear and circular motion.
- Determine the speed of the points A, B, and C **with respect to the ground** for the bicycle that is moving at a constant speed of 4 m/s.
- Determine the speed of the points A, B, and C **with respect to the bicycle**, assuming the bicycle is moving at a constant speed of 4 m/s.



# Ch.5 Review: Rolling without skidding

$S$  frame: the ground



$S'$  frame: the axle  
 $\vec{V} = v$ , to the right

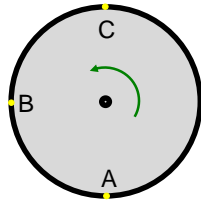
The wheel rotates counterclockwise (CCW).

The tangential speed of a point on the rim is  $v = 4$  m/s, relative to the axle.

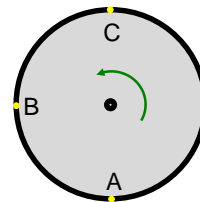
In “rolling without skidding”, the axle moves at speed  $v$ . This is the  $S'$  frame.


# Ch.5 Review: Rolling without skidding

$S'$  bicycle frame:  
the axle is at rest



$S$  ground frame: the  
ground is at rest



$\vec{V}$  is the velocity of the axle relative to the ground.  


$$\vec{v} = \vec{v}' + \vec{V}$$

# Ch.5 Review: Rolling without skidding

[← Homework 5](#)

**Problem 5.11**

- Determine the speed of the points A, B, and C **with respect to the bicycle**, assuming the bicycle is moving at a constant speed of 4 m/s. Rotation only:

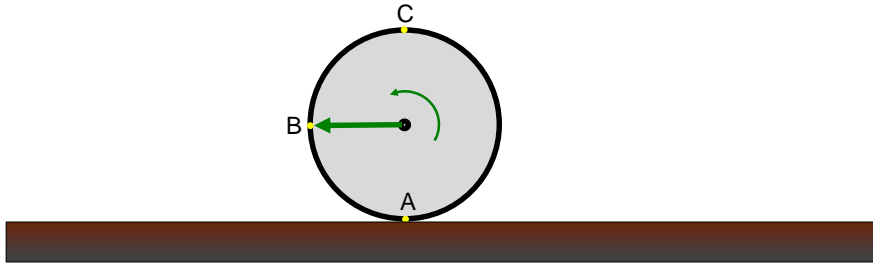
C: **4 m/s** to the left.  
 B:  $0 + 4 \text{ m/s}$  to the left = **0 m/s**.  
 A: **4 m/s** to the right.

- Determine the speed of the points A, B, and C **with respect to the ground** for the bicycle that is moving at a constant speed of 4 m/s. Add linear motion:

C:  $4 \text{ m/s}$  to the left +  $4 \text{ m/s}$  to the left = **8 m/s** to the left.  
 B:  $0 + 4 \text{ m/s}$  to the left = **4 m/s** to the left.  
 A:  $4 \text{ m/s}$  to the right +  $4 \text{ m/s}$  to the left = **0 m/s**



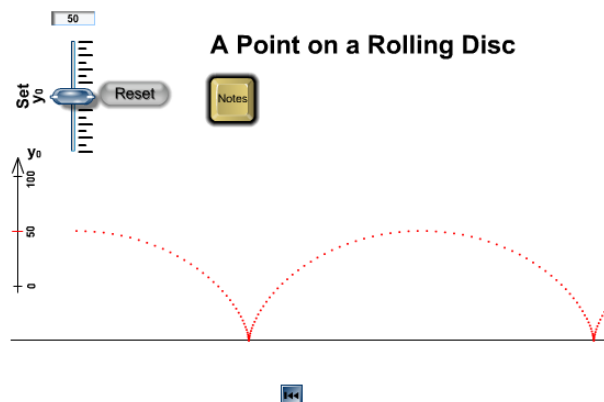
## Ch.5 Review: Rolling without skidding



- In “rolling without skidding”, point A, which is touching the ground, has a momentary velocity of **zero**!
- That means, if your car is accelerating or decelerating or turning, it is *static friction* of the road on the wheels that provides the net force which accelerates the car

## Rolling without skidding Animation

<https://faraday.physics.utoronto.ca/GeneralInterest/Harrison/Flash/ClassMechanics/RollingDisc/RollingDisc.html>



Copyright © 2004 David M. Harrison

## Ch.5 Review: Rolling without skidding



- No matter what the speed, four points on this car are always **at rest!**
- Which points? The bottoms of the four tires!



- A wheel rolls much like the treads of a tank.
- The bottom of the wheel is **at rest** relative to the ground as it rolls.

## Ch.5 Review: Learning Catalytics Question (part 1 of 2)

You are sitting in your car, and you step on the gas pedal. The car accelerates forward.

Since the car has a large forward acceleration, there must be a large forward force acting on the car,  $\vec{F}_{1 \text{ on } 2}$ .

Here, object 2 is the car.

What is object 1?

- A. The road
- B. The engine
- C. The air
- D. The gas pedal
- E. An invisible string attached to the front of the car

## Ch.5 Review: Learning Catalytics Question (part 2 of 2)

You are sitting in your **Car**, and you step on the gas pedal. The car accelerates forward, due to the large forward force from the **Road**,

$\vec{F}_{E \text{ on } R}$

What kind of force is  $\vec{F}_{E \text{ on } R}$ ?

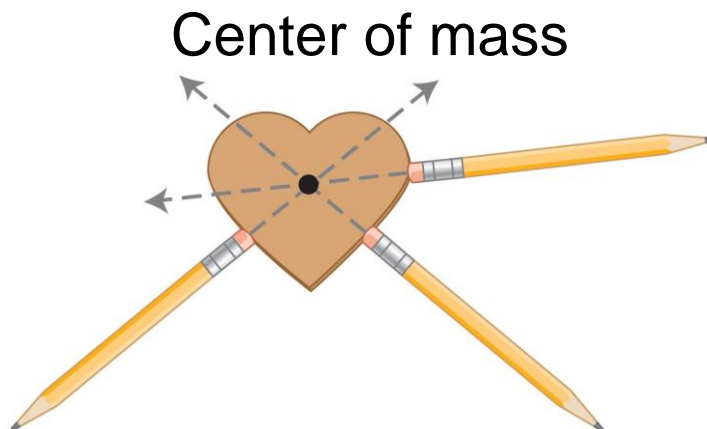
- |                     |                    |
|---------------------|--------------------|
| A. air resistance   | F. normal          |
| B. applied force    | G. spring force    |
| C. electric         | H. static friction |
| D. kinetic friction | I. tension         |
| E. magnetic         | J. thrust          |

## What's the Big Idea of Chapters 8 and 9?

- So far we've kind of been neglecting the fact that objects have size and shape.
- This has been the "point particle" approximation.
- For this chapter we will start thinking about "extended bodies", which just means objects that are not points, but have some shape and size.
- Force, momentum and energy are still important, but there are some new things, like:
  - **Torque:** kind of like force (with different units), but it's what gets objects turning.
  - **Rotation:** things can spin or roll!



- A **rigid body** is a model for an extended object.
- We assume that the object has a nonzero size but the distances between all parts of the object remain the same (the size and shape of the object do not change).

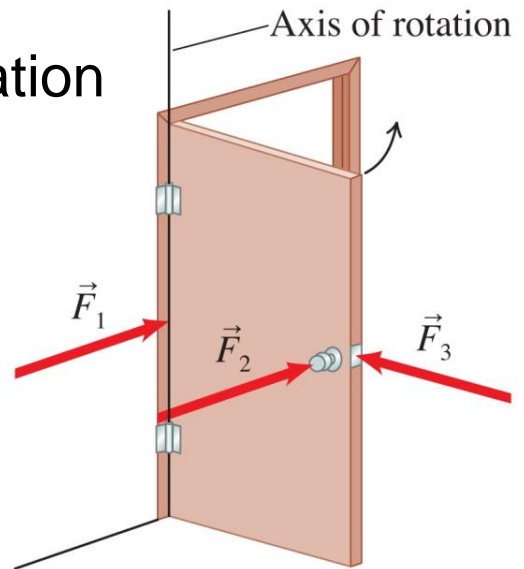


- A rigid body possesses a special point such that if a force is exerted on that point, the object will not turn.
- We call this point the object's center of mass.



## Axis of rotation

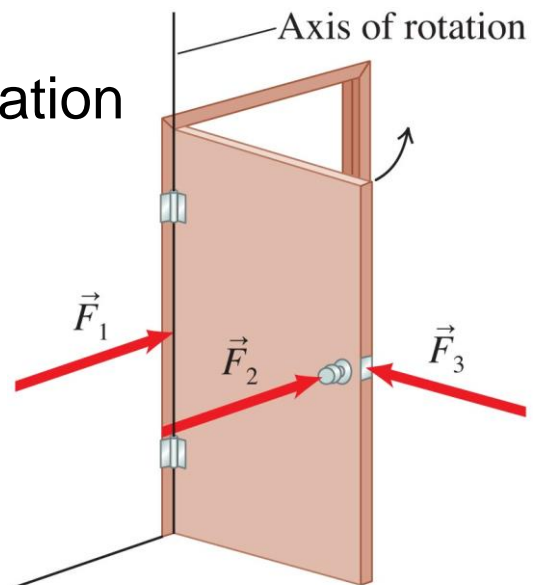
- When objects turn around an axis, physicists say that they undergo **rotational** motion.
- We call the imaginary line passing through the hinges the **axis of rotation**.



$\vec{F}_1$  and  $\vec{F}_3$  do not rotate the door, whereas  $\vec{F}_2$  moves it easily.

## Causing rotation

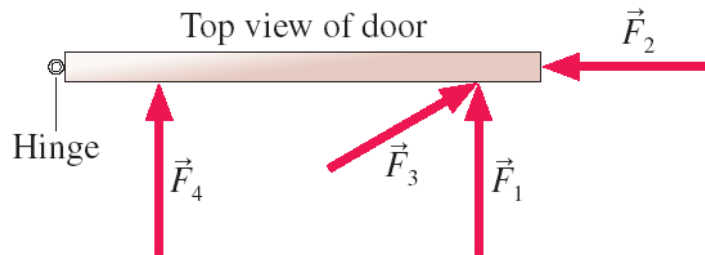
- Three factors affect the turning ability of a force:
  1. The **place** where the force is exerted
  2. The **magnitude** of the force
  3. The **direction** in which the force is exerted



$\vec{F}_1$  and  $\vec{F}_3$  do not rotate the door, whereas  $\vec{F}_2$  moves it easily.

## Learning Catalytics Question

Consider the common experience of pushing open a door. Shown is a top view of a door hinged on the left. Four pushing forces are shown, all of equal strength. Which of these will be most effective at opening the door?



- A.  $F_1$
- B.  $F_2$
- C.  $F_3$
- D.  $F_4$

## Torque $\tau$ produced by a force

**Torque  $\tau$  produced by a force** The torque produced by a force exerted on a rigid body about a chosen axis of rotation is

$$\tau = \pm Fl \sin \theta$$

where  $F$  is the magnitude of the force,  $l$  is the magnitude of the distance between the point where the force is exerted on the object and the axis of rotation, and  $\theta$  is the angle that the force makes relative to a line connecting the axis of rotation to the point where the force is exerted

- The SI unit of force is the Newton-meter (N-m).

[Doc Cam example]

Luis uses a 20 cm long wrench to turn a nut. The wrench handle is tilted 30° above the horizontal, and Luis pulls straight down on the end with a force of 100 N. How much torque does Luis exert on the nut?

Sketch and translate

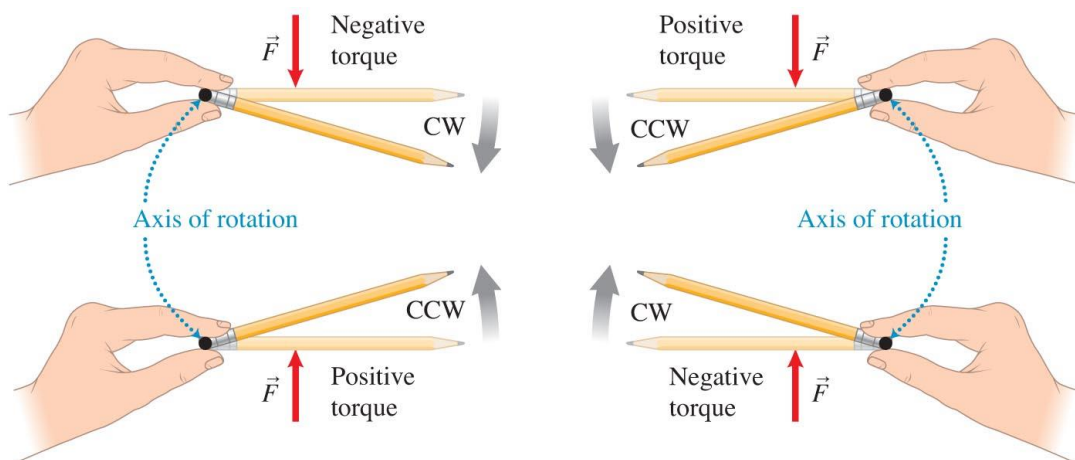
Represent mathematically

Simplify and diagram

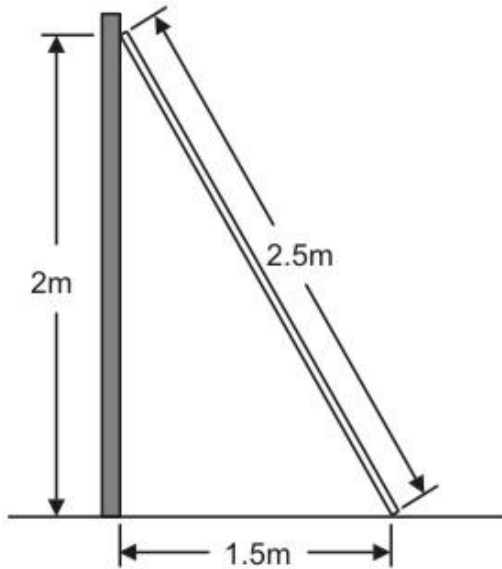
Solve and Evaluate

## Sign Convention for Torque (historical)

- If the torque tends to produce a **counterclockwise** rotation, this is **positive** torque.
- If the torque tends to produce **clockwise** rotation, this is **negative** torque.

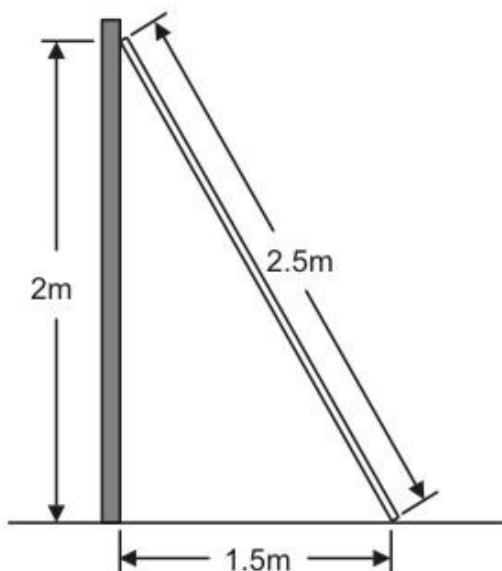


## Learning Catalytics Question



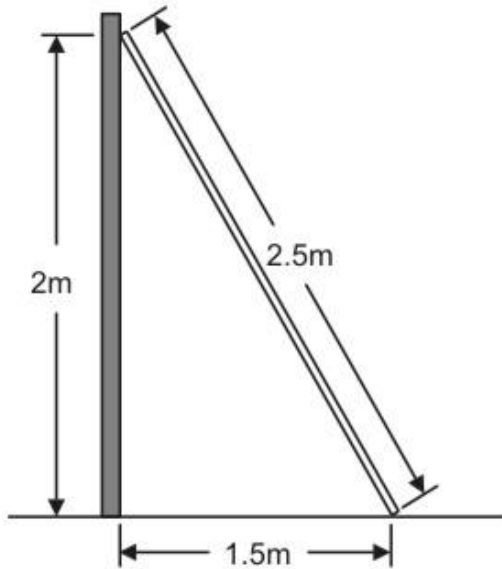
- A ladder leans against a wall.
  - What is the sign of the torque of the normal force of the wall on the ladder,  $N_{W \text{ on } L}$ ?
- A. Positive  
B. Negative  
C. The torque is zero  
D. It depends on where we choose the rotation axis to be

## Learning Catalytics Question



- A ladder leans against a wall.
  - Let's choose the rotation axis to be at the bottom of the ladder.
  - What is the sign of the torque of the normal force of the wall on the ladder,  $N_{W \text{ on } L}$ ?
- A. Positive  
B. Negative  
C. The torque is zero

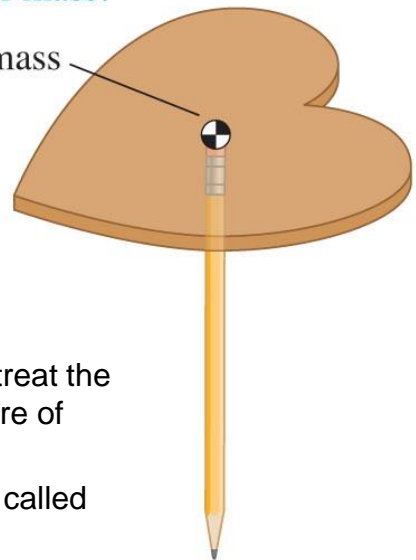
## Learning Catalytics Question



- A ladder leans against a wall.
  - Let's choose the rotation axis to be at the bottom of the ladder.
  - What is the sign of the torque of the static friction force of the floor on the ladder,  $f_{s \text{ F on L}}$ ?
- A. Positive  
B. Negative  
C. The torque is zero

The heart does not tip if supported under its center of mass.

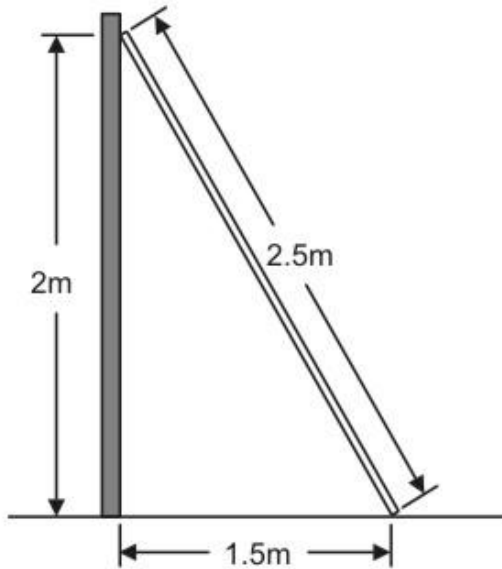
Center of mass



Where is the gravitational force exerted on a rigid body?

- When calculating the torque due to gravity, you may treat the object as if all its mass were concentrated at the centre of mass.
- That is why the object's center of mass is sometimes called the object's **centre of gravity**.

## Learning Catalytics Question



- A uniform ladder leans against a wall.
  - Let's choose the rotation axis to be at the bottom of the ladder.
  - What is the sign of the torque of the force of gravity of the Earth on the ladder,  $F_{g \text{ E on L}}$ ?
- A. Positive  
B. Negative  
C. The torque is zero

## Reading Week

- Nov. 5 - 9 is the "Fall Reading Week" – No Classes!
- So, I'll see you on Monday Nov. 12! We'll continue with Static Equilibrium problems from Chapter 8.
- And don't forget there's a test on Tue. Nov.13!
- Until then... have a great break!

