

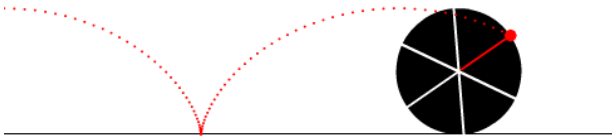
# PHY131H1F - Class 17

Today:

Finishing Chapter 10:

Rolling Without Slipping

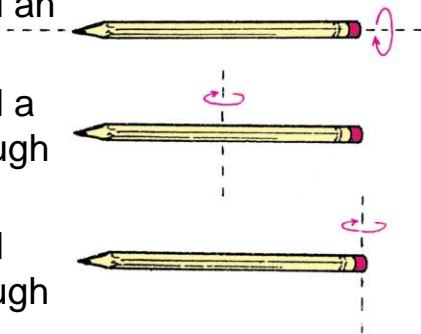
Rotational Energy



## Learning Catalytics Question 1

Which pencil has the largest rotational inertia?

- A. The pencil rotated around an axis passing through it.
- B. The pencil rotated around a vertical axis passing through centre.
- C. The pencil rotated around vertical axis passing through the end.



## 10.5: Rolling without slipping



- No matter what the speed, four points on this car are always **at rest!**
- Which points? The bottoms of the four tires!

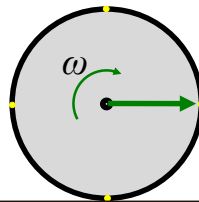


- A wheel rolls much like the treads of a tank.
- The bottom of the wheel is **at rest** relative to the ground as it rolls.

## Rolling without slipping

$S$  frame: the ground

$S'$  frame: the axle  
 $\vec{V} = v$ , to the right



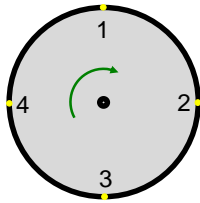
The wheel rotates with angular speed  $\omega$ .

The tangential speed of a point on the rim is  $v = \omega r$ , relative to the axle.

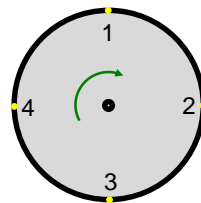
In “rolling without slipping”, the axle moves at speed  $v$ . This is the  $S'$  frame.


# Rolling without slipping

$S'$  frame: the axle  
is at rest



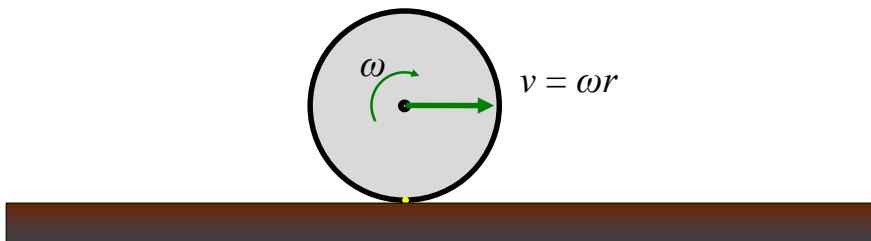
$S$  frame: the ground  
is at rest



$\vec{V}$  is the velocity of the axle relative to the ground.  


$$\vec{v} = \vec{v}' + \vec{V}$$

# Rolling without slipping



The wheel rotates with angular speed  $\omega$ .

The axle moves with linear speed  $v = \omega r$ ,  
where  $r$  is the radius of the wheel.

- If your car is accelerating or decelerating or turning, it is *static friction* of the road on the wheels that provides the net force which accelerates the car

# Rolling without slipping Doc Cam Demo

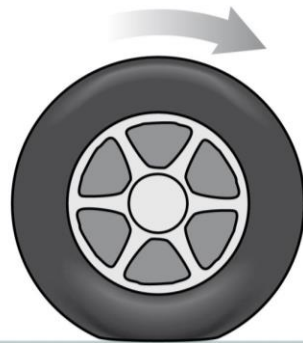
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## Rolling Without Slipping

- Under normal driving conditions, the portion of the rolling wheel that contacts the surface is *stationary*, not sliding
- In this case the speed of the centre of the wheel is:

$$v = \frac{C}{T}$$

where  $C$  = circumference [m] and  $T$  = Period [s]



## Example

- The circumference of the tires on your car is 0.9 m.
- The onboard computer in your car measures that your tires rotate 10 times per second.
- What is the speed as displayed on your speedometer?



## The “Rolling Without Slipping” Constraints

When a round object rolls without slipping, the distance the axis, or centre of mass, travels is equal to the change in angular position times the radius of the object.

$$s = \theta R$$

The speed of the centre of mass is

$$v = \omega R$$

The acceleration of the centre of mass is

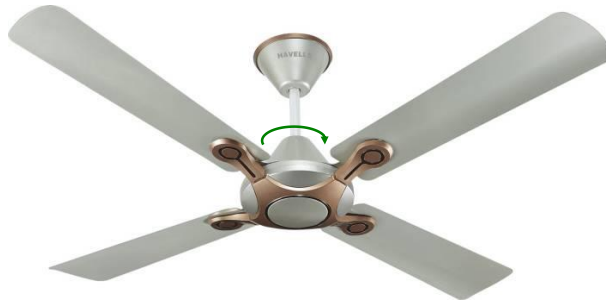
$$a = \alpha R$$



## Rotational Kinetic Energy

A rotating rigid body has kinetic energy because all atoms in the object are in motion. The kinetic energy due to rotation is called **rotational kinetic energy**.

$$K_{\text{rot}} = \frac{1}{2}I\omega^2$$



Example: A 0.50 kg basketball rolls along the ground at 1.0 m/s. What is its *total* kinetic energy (linear plus rotational)? [Note that the rotational inertia of a hollow sphere is  $I = \frac{2}{3}MR^2$ .]

# Linear / Rotational Analogy

	Linear	Rotational Analogy
	<ul style="list-style-type: none"><li>• <math>\vec{s}, \vec{v}, \vec{a}</math></li><li>• Force: <math>\vec{F}</math></li><li>• Mass: <math>m</math></li></ul>	<ul style="list-style-type: none"><li>• <math>\theta, \omega, \alpha</math></li><li>• Torque: <math>\tau</math></li><li>• Rotational Inertia: <math>I</math></li></ul>
• Newton's 2 <sup>nd</sup> law:	$\vec{a} = \frac{\vec{F}_{net}}{m}$	$\alpha = \frac{\tau_{net}}{I}$
• Kinetic energy:	$K_{cm} = \frac{1}{2}mv^2$	$K_{rot} = \frac{1}{2}I\omega^2$

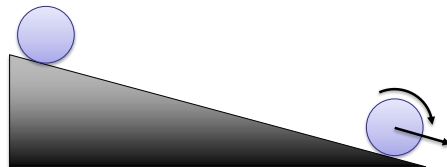
## Summary of some Different Types of Energy:

- Kinetic Energy due to linear motion of centre of mass:  $K = \frac{1}{2}mv^2$
- Gravitational Potential Energy  $U_g = mgh$
- Spring Potential Energy:  $U_s = \frac{1}{2}kx^2$
- Rotational Kinetic Energy:  $K_{rot} = \frac{1}{2}I\omega^2$
- Thermal Energy:  $\Delta E_{th}$  (often created by kinetic friction)
  - An object can possess any or all of the above.
  - One way of transferring energy to or out of an object is work:
- Work done by a constant force:  $W = Frcos\theta$

- Learning Catalytics Q2
- A hoop and a disk are both released from rest at the top of an incline. They both roll without slipping. Which reaches the bottom first? Shall we vote?
- A: hoop wins
- B: disk wins
- C: tie

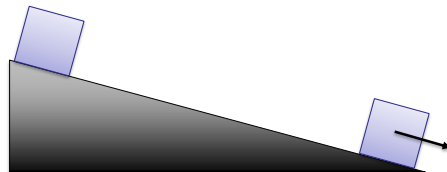


Don't forget: Nature is not a democracy!



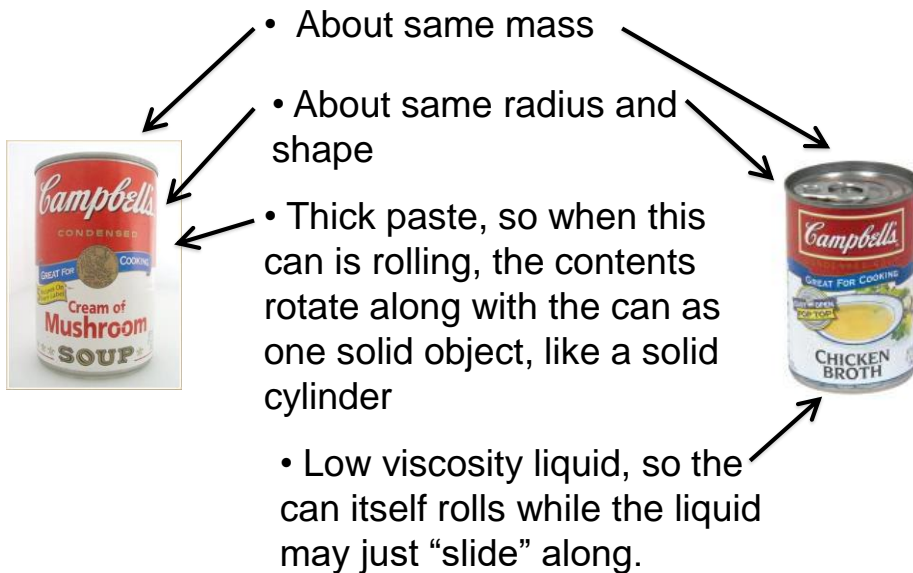
- Learning Catalytics Q3. A solid disk is released from rest and rolls without slipping down an incline. A box is released from rest and slides down a frictionless incline of the same angle. Which reaches the bottom first?

- A: disk wins
- B: box wins
- C: tie





## Compare and Contrast Soup Cans



## Learning Catalytics Q4

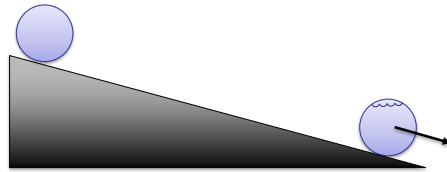
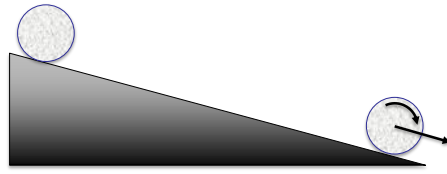
- Two soup cans begin at the top of an incline, are released from rest, and allowed to roll without slipping down to the bottom. Which will win?



Predict:

- A. Cream of Mushroom will win
- B. Chicken Broth will win
- C. Both will reach the bottom at about the same time.

- Cream of Mushroom soup must rotate, like a solid disk.
- Chicken broth can slide down **without rotating** while the can rotates around it.



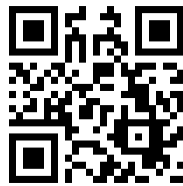
1. What is the acceleration of a slipping object down a ramp inclined at angle  $\theta$ ? [assume no friction]

2. What is the acceleration of a **solid disk** rolling down a ramp inclined at angle  $\theta$ ? [assume rolling without slipping]

3. What is the acceleration of a **hoop** rolling down a ramp inclined at angle  $\theta$ ? [assume rolling without slipping]

## Before Class 18 on Monday

- The reading is all of Chapter 11 on Rotational Vectors and Angular Momentum.
- Please read the chapter and/or watch the Preclass 18 Video.



- Something to think about: When a figure-skater starts a spin and brings in her arms, she spins even faster. Why?

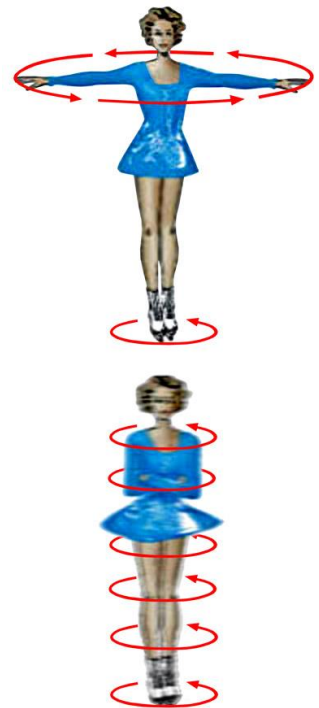


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