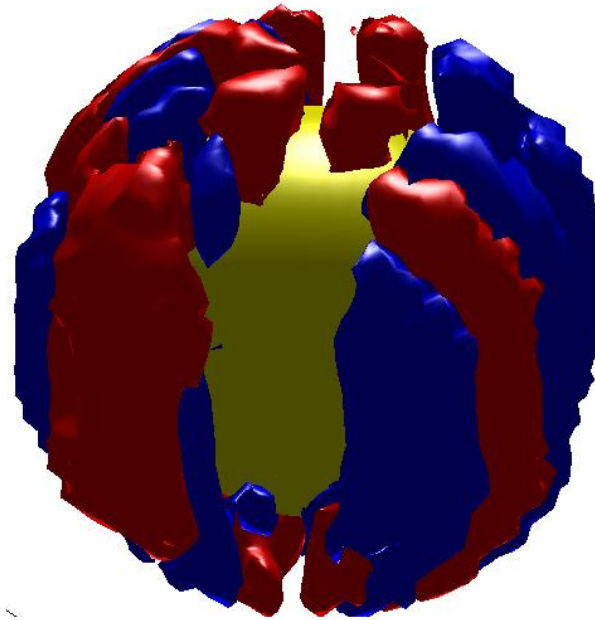


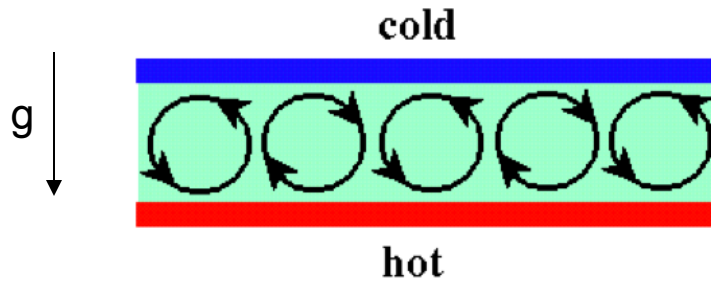
# Fluid Dynamics of Planetary Cores



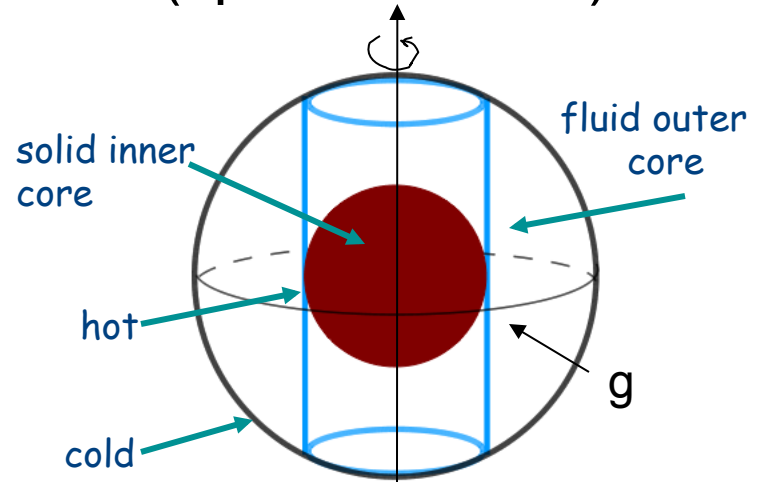
PHY1530: Fluid Dynamics

# Geometry

Rayleigh Benard Convection: (planar)



Core Convection: (spherical shell)



other differences:

- spherical shell is rotating
- gravity in radial direction
- magnetic fields!

# How Planets Make Magnetic Fields

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## Dynamo action:

complex motions + electrically conducting fluid + presence of a magnetic field  $\implies$  maintain magnetic field against Ohmic decay

---

## Magnetic Induction Equation:

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) + \frac{1}{\sigma\mu} \nabla^2 \vec{B}$$

change                      creation                      destruction

(can derive from Maxwell's eqn's & Ohm's law)

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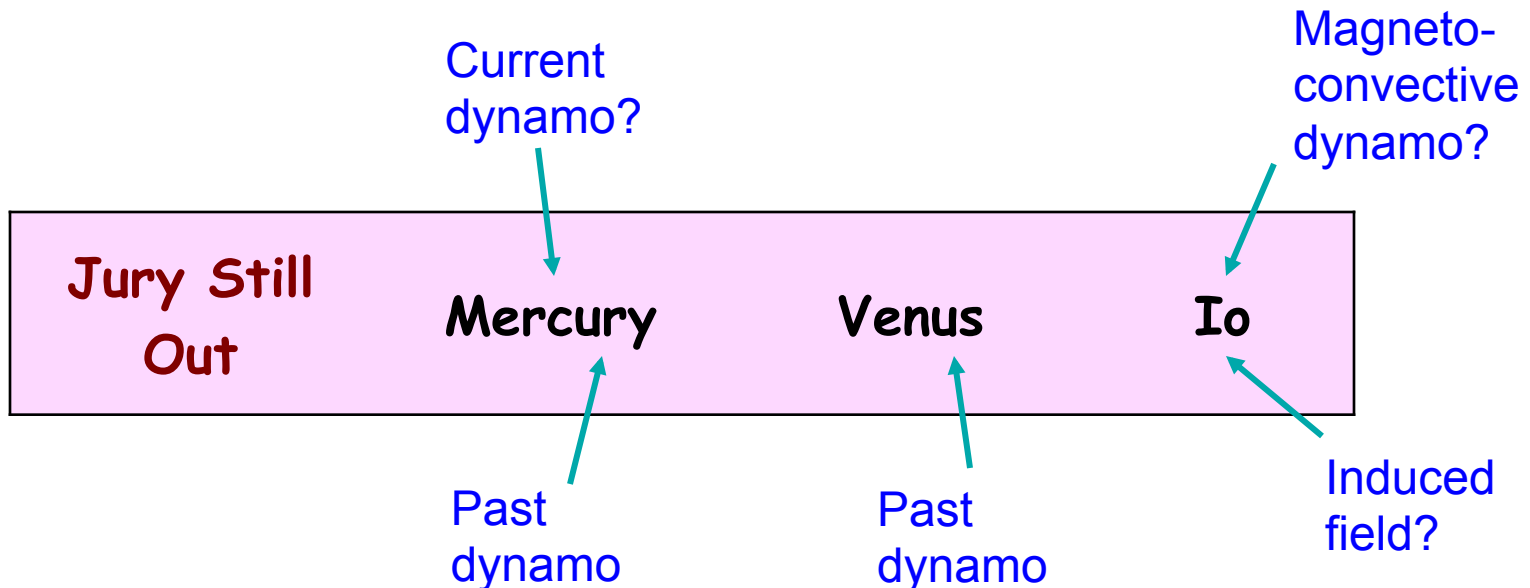
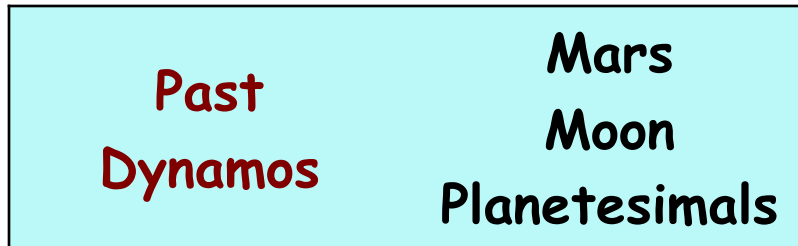
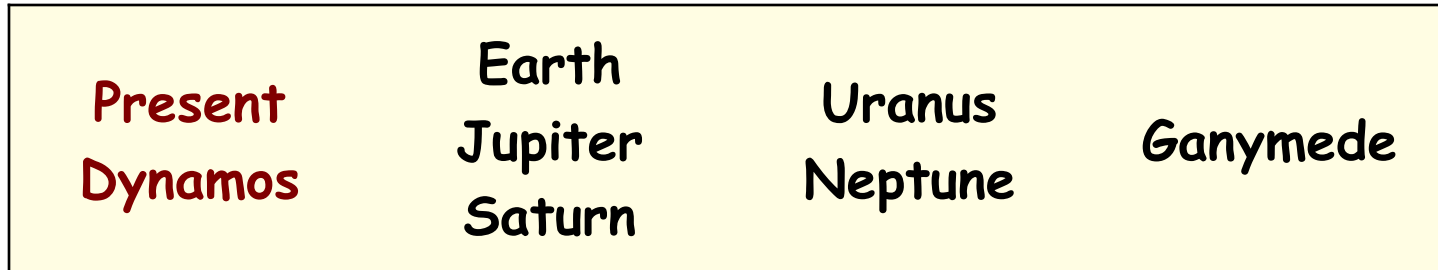
Necessary condition for dynamo action:

Magnetic Reynolds number:  $R_m = \frac{\nabla \times (v \times B)}{\frac{1}{\sigma\mu} \nabla^2 B} \approx \sigma\mu VL$

- For dynamo action in a fluid, we need  $R_m > 10-100$
- For Earth's core:  $R_m \sim 500$ , for a sphere of copper:  $R_m \sim 6$ , for a typical star:  $R_m \sim 10^9$

# Summary of Planetary Dynamos

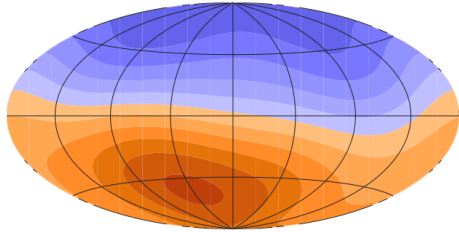
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# Comparing Planetary Magnetic Fields

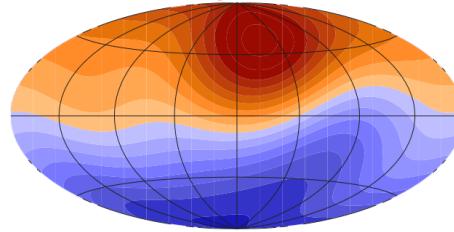
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Earth



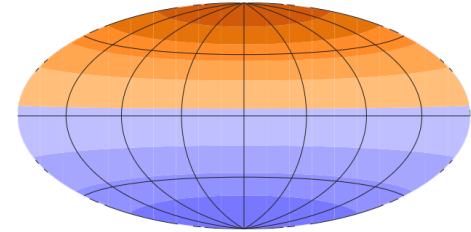
+0.1mT -0.1mT

Jupiter



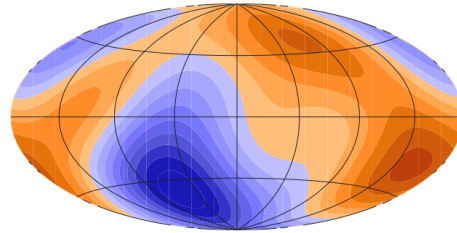
+1mT -1mT

Saturn



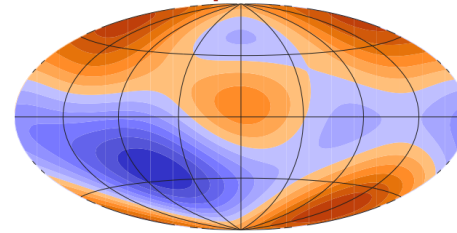
+0.1mT -0.1mT

Uranus



+0.1mT -0.1mT

Neptune



+0.1mT -0.1mT

# Dimensional dynamo equations (using Boussinesq approximation)

$$\mathbf{N-S:} \left( \frac{\partial}{\partial t} + \vec{v} \cdot \nabla \right) \vec{v} + 2\vec{\Omega} \times \vec{v} = -\nabla p + \frac{\Delta \rho}{\rho} \vec{g} + \nu \nabla^2 \vec{v} + \frac{1}{\rho \mu} (\nabla \times \vec{B}) \times \vec{B}$$

$$\text{Continuity:} \quad \nabla \cdot \vec{v} = 0$$

$$\text{Magnetic Induction:} \quad \left( \frac{\partial}{\partial t} - \eta \nabla^2 \right) \vec{B} = \nabla \times (\vec{v} \times \vec{B})$$

$$\text{Energy:} \quad \left( \frac{\partial}{\partial t} - \kappa \nabla^2 \right) T = -\vec{v} \cdot \nabla T$$

$\vec{v}$  : velocity

$\vec{\Omega}$  : rotation vector

$p$  : modified pressure

$\rho$  : density

$\Delta \rho$  : density perturbation

$\vec{g}$  : gravity

$\nu$  : viscosity

$\vec{j}$  : current density

$\vec{B}$  : magnetic field

$\eta$  : magnetic diffusivity =  $(\sigma \mu_0)^{-1}$

$\sigma$  : electrical conductivity

$\mu_0$  : magnetic permeability

$\kappa$  : thermal diffusivity

$T$  : temperature

## Differences with RBC equations

N-S:  $\left(\frac{\partial}{\partial t} + \vec{v} \cdot \nabla\right) \vec{v} + \underbrace{2\vec{\Omega} \times \vec{v}}_{\text{Coriolis force}} = -\nabla p + \frac{\Delta \rho}{\rho} \vec{g} + \nu \nabla^2 \vec{v} + \underbrace{\frac{1}{\rho \mu} (\nabla \times \vec{B}) \times \vec{B}}_{\text{Lorentz force}}$

Continuity:  $\nabla \cdot \vec{v} = 0$

Magnetic Induction:  $\left(\frac{\partial}{\partial t} - \eta \nabla^2\right) \vec{B} = \nabla \times (\vec{v} \times \vec{B})$

advection

diffusion

needed new equation for new variable 'B' in N-S

Energy:  $\left(\frac{\partial}{\partial t} - \kappa \nabla^2\right) T = -\vec{v} \cdot \nabla T$

## Non-dimensionalize:

Length:

$$r = r_0 r'$$

$r_0$  : core radius

Time

$$t = \tau_\eta t' = \frac{r_0^2}{\eta} t'$$

$\tau_\eta$  : magnetic diffusion time

Velocity

$$v = \frac{r_0}{\tau_\eta} v' = \frac{\eta}{r_0} v'$$

Temperature

$$T = \Delta T T'$$

$h_T$  : heat flux at inner boundary

Magnetic field

$$B = B_{\Lambda=1} B' = \sqrt{2\Omega\rho\mu\eta} B'$$

$B_{\Lambda=1}$  : Elsasser number=1 scale

pressure

$$P = 2\Omega\eta\rho_0 P'$$

and use equation of state (dimensional):  $\Delta\rho = -\rho_0\alpha(T - T_0)$

and a linear approximation for gravity (dimensional):  $\vec{g} = -g_0\vec{r} / r_0$

Plug into the equations, simplify and remove the primes gives....



## Non-dimensional equations

**N-S:**  $Ro_M \left( \frac{\partial}{\partial t} + \vec{v} \cdot \nabla \right) \vec{v} + \hat{z} \times \vec{v} = -\nabla p + Ra(T - T_0)\vec{r} + E\nabla^2 \vec{v} + \vec{J} \times \vec{B}$

inertia
Coriolis
pressure gradient
buoyancy
viscous
Lorentz

**MIE:**  $\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) + \nabla^2 \vec{B}$

**Energy:**  $\left( \frac{\partial}{\partial t} - q_k \nabla^2 \right) T = -\vec{v} \cdot T$

**Continuity:**  $\nabla \cdot \vec{v} = 0$

Notice: 4 non-dimensional numbers:

$Ro_M, Ra, E, q_k$

(ie 4 independent control parameters)

# Non-dimensional numbers

(Input)		Earth's core	
Magnetic Rossby #:	$Ro_M = \frac{\eta}{2\Omega L^2}$	$10^{-9}$	
Ekman #:	$E = \frac{\nu}{2\Omega L^2}$	$10^{-15}$	
Modified Rayleigh #:	$Ra = \frac{\alpha_T g_0 h_T r_0^2}{2\Omega \eta}$	?	buoyancy/coriolis since rotation is main hindrance to convection
Roberts #:	$q_\kappa = \frac{\kappa}{\eta}$	$10^{-6}$	
↓			
Prandtl #:	$Pr = \frac{\nu}{\kappa}$	$10^{-1} \rightarrow 10^{-2}$	(dependent on other 4)
<hr/>			
(Output)			
Magnetic Reynolds #:	$Re_M = \frac{UL}{\eta}$	750	Using velocities near CMB
Kinetic Reynolds #:	$Re = \frac{UL}{\nu}$	$1.5 \times 10^9$	Using velocities near CMB
Elsasser #:	$\Lambda = \frac{B^2}{2\Omega \rho \mu_0 \eta}$	$O(1)$	Using magnetic field near CMB
Rossby #:	$Ro = \frac{U}{2\Omega L}$	$10^{-6}$	Using velocities near CMB

## Comparing planets

	Earth	Ganymede	Jupiter	Uranus
$\Omega$ , rotation rate ( $s^{-1}$ )	$7 \times 10^{-5}$	$1 \times 10^{-5}$	$2 \times 10^{-4}$	$1.4 \times 10^{-5}$
Density ( $kg/m^3$ )	$1.1 \times 10^4$	$6 \times 10^3$	$1 \times 10^3$	$1 \times 10^3$
Size of dynamo region (m)	$3 \times 10^6$	$7 \times 10^5$	$3 \times 10^7$	$\sim 1 \times 10^7$
$H_T$ , temperature scale height (m)	$1 \times 10^7$	$4 \times 10^7$	$1 \times 10^8$	$1 \times 10^7$
Conductive heat flow along adiabat ( $W/m^2$ )	$1.5 \times 10^{-2}$	$1 \times 10^{-3}$	$< 10^{-1}$	$< 10^{-2}$
Nominal convective heat flow ( $W/m^2$ )	$1 \times 10^{-2}$	$1 \times 10^{-3}$	3	$\sim 10^{-1}$
Magnetic diffusivity ( $m^2/s$ )	2	4	30	$\sim 100$
$R_m$ based on $v_{ml}$	$3 \times 10^3$	70	$3 \times 10^4$	700
$R_m$ based on $v_{mac}$	50	5	400	25
$\Lambda$ , Elsasser number at top of dynamo	0.3	0.3	0.3	$\sim 0.01?$

$Ro_M = \frac{\eta}{2\Omega L^2}$	$1.5 \times 10^{-9}$	$2 \times 10^{-7}$	$8 \times 10^{-11}$	$3 \times 10^{-8}$
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$E = \frac{\nu}{2\Omega L^2}$	$7.6 \times 10^{-16}$	$5 \times 10^{-14}$	$2 \times 10^{-18}$	$3 \times 10^{-16}$
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$q_\kappa = \frac{\kappa}{\eta}$	$2.5 \times 10^{-6}$	$1.2 \times 10^{-6}$	$1.6 \times 10^{-7}$	$5 \times 10^{-8}$
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## Some Rotating MHD

$$Ro_M \left( \frac{\partial}{\partial t} + \vec{v} \cdot \nabla \right) \vec{v} + \hat{z} \times \vec{v} = -\nabla p + Ra(T - T_0)\vec{r} + E\nabla^2 \vec{v} + \vec{J} \times \vec{B}$$

Start simple

- no magnetic field, buoyancy
- consider mainstream flow (inertia & viscosity small)
- dominant force balance given by:

$$\hat{z} \times \vec{v} = -\nabla p$$

-take curl of equation to get:

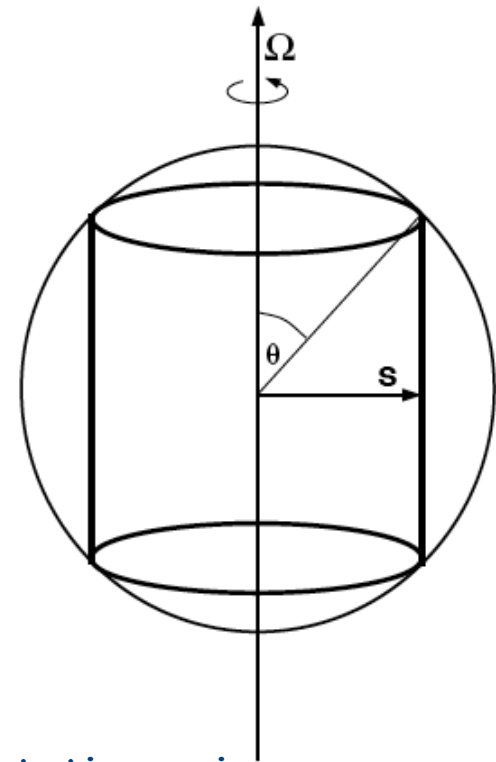
$$\frac{\partial \vec{v}}{\partial z} = 0 \quad \text{"Taylor Proudman Theorem"}$$

- main force balance requires z-independent motion
- non-penetrative boundary conditions & continuity

eq'n give:

$$\vec{v} = V_G(s)\hat{\phi}$$

-i.e. motion constrained to cylinders coaxial with the rotation axis, called "geostrophic flow":



## Some Rotating MHD

Add buoyancy: 2 effects:

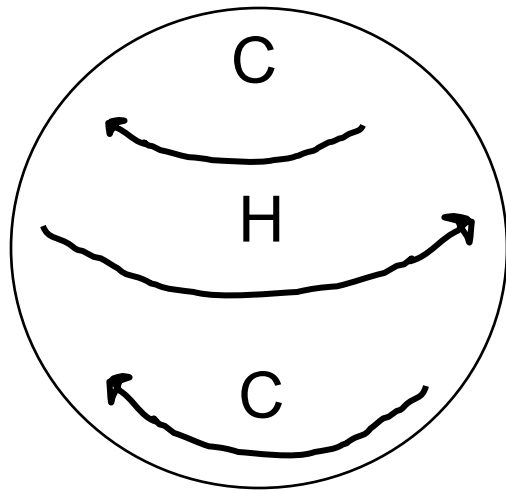
(1) Thermal Winds

$$2\rho\vec{\Omega} \times \vec{v} = -\nabla p - \rho\alpha\Theta\vec{g}$$

take curl:

$$\frac{\partial \vec{v}}{\partial z} = \frac{\alpha}{2\Omega} (\vec{g} \times \nabla \Theta)$$

so if temp. varies with latitude or longitude, it can cause variations of velocity in the z direction, but not in "r" direction (b/c g in r direction)



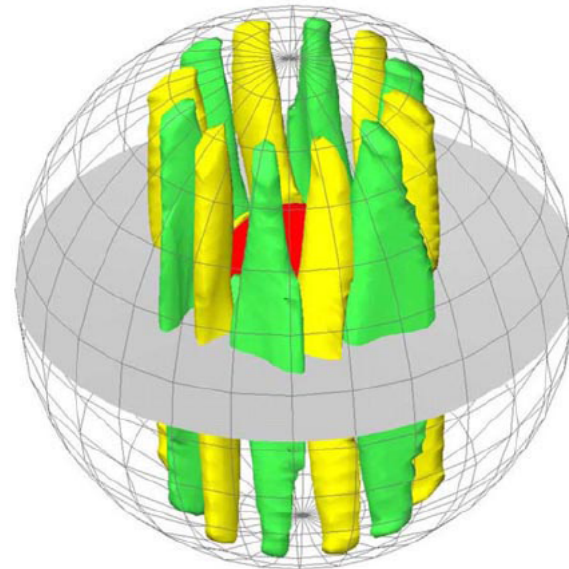
(2) Convection

-geostrophic flows & thermal winds can't transport heat from interior to CMB (no radial motion)

-convective motions require presence of other forces (viscous, inertia, magnetic) to offset effect of rotation (Taylor-Proudman Theorem)

-however, convection still satisfies Taylor-Proudman theorem to leading order (derivatives in z much smaller than other directions)

-convection at onset:



## Some Rotating MHD

Now lets add a magnetic field:

- either Lorentz force is part of dominant force balance
- or its not

If it is:  $2\rho\vec{\Omega} \times \vec{v} = -\nabla p + \vec{J} \times \vec{B} - \rho\alpha\Theta\vec{g}$  "magnetostrophic balance"

Can determine necessary B magnitude for this balance

$$|2\rho\vec{\Omega} \times \vec{v}| \sim |\vec{J} \times \vec{B}| \Rightarrow B \sim \sqrt{2\Omega\rho\mu\eta}$$

## Weak & Strong Dynamos

$$Ro_M \left( \frac{\partial}{\partial t} + \vec{v} \cdot \nabla \right) \vec{v} + \hat{z} \times \vec{v} = -\nabla p + Ra(T - T_0)\vec{r} + E\nabla^2 \vec{v} + \vec{J} \times \vec{B}$$

If Lorentz force part of dominant balance:

- “strong field dynamo”, magnetic field is stronger
- convection is ‘easier’ (i.e. lower critical Ra #) b/c magnetic field balances Coriolis force, easing rotational constraint
- so planets want to be in this regime

If it isn't:

- “weak field dynamo”, magnetic field generally weaker
- rotational constraint makes convection difficult
- magnetic field doesn't affect velocity field so much (Lorentz force is small)

## Why not ignore viscosity and inertia?

- involved in balancing deviations from a Taylor state --> important dynamically
- without them:

$$\hat{z} \times \mathbf{u} = -\nabla p + \mathbf{j} \times \mathbf{B} + R_a \Theta \hat{r},$$

$$\implies \int_{\Sigma} (\mathbf{j} \times \mathbf{B})_{\phi} dS = 0, \quad (\text{Taylor State})$$

- in a Taylor state, magnetic torques on surface of cylinders in the core vanish
- this is a major constraint on the structure of the magnetic field

- with inertia and viscosity, can balance the Lorentz torque:

$$R_o(1-s^2)^{\frac{1}{2}} \frac{\partial u_{\phi}(s)}{\partial t} + E^{\frac{1}{2}}(1-s^2)^{-\frac{1}{4}} u_{\phi}(s) = \frac{1}{4\pi s} \int_{\Sigma} (\mathbf{j} \times \mathbf{B})_{\phi} dS.$$

↑  
inertia
↑  
viscosity

viscosity: lorentz torque scales with  $u$ , so any initial torque results in motion that acts to decrease torque. Eventually torque=0 and  $u=0$  and you are in a Taylor state

inertia: lorentz torque scales with acceleration  $du/dt$ , so any initial torque results in acceleration. When torque=0, still have  $u$ , so you overshoot --> "Torsional oscillations"

Note: also can't ignore viscosity b/c of degree of equation



# Evidence for torsional oscillations

-is there any evidence for torsional oscillations? Yes! observational evidence in length of day records and geomagnetic jerks

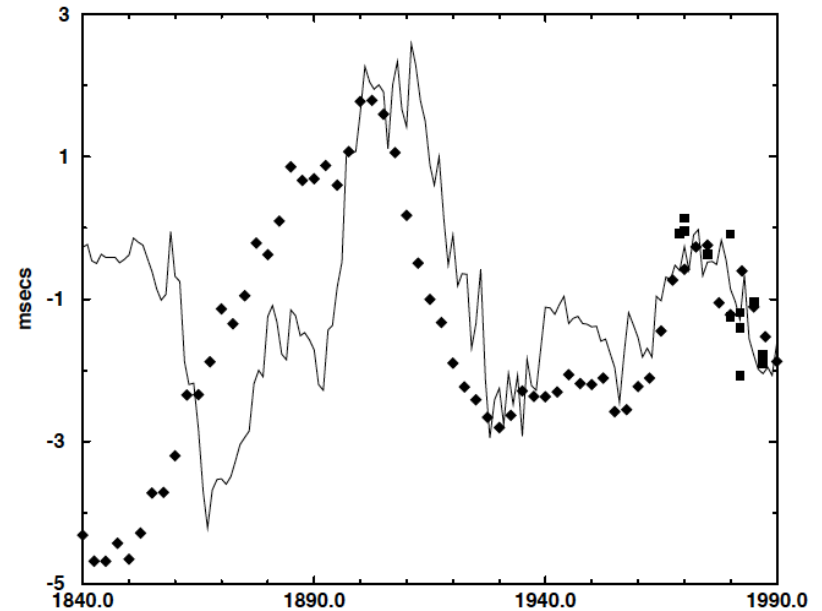
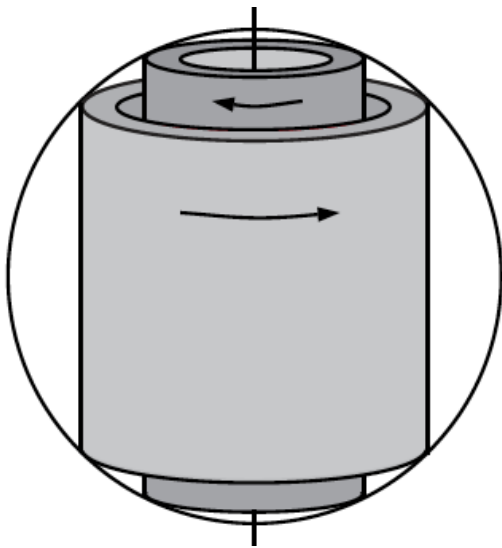
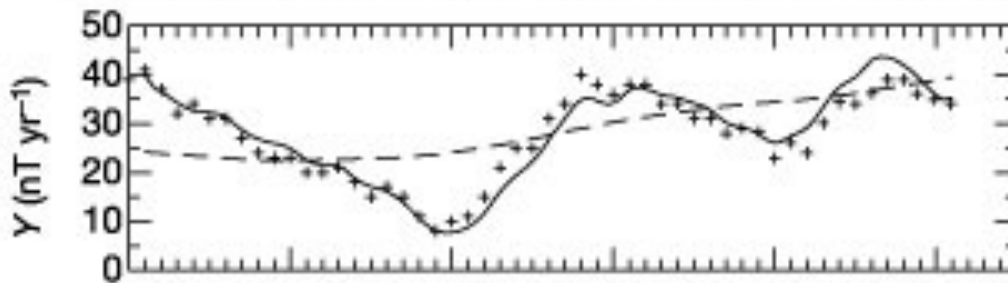
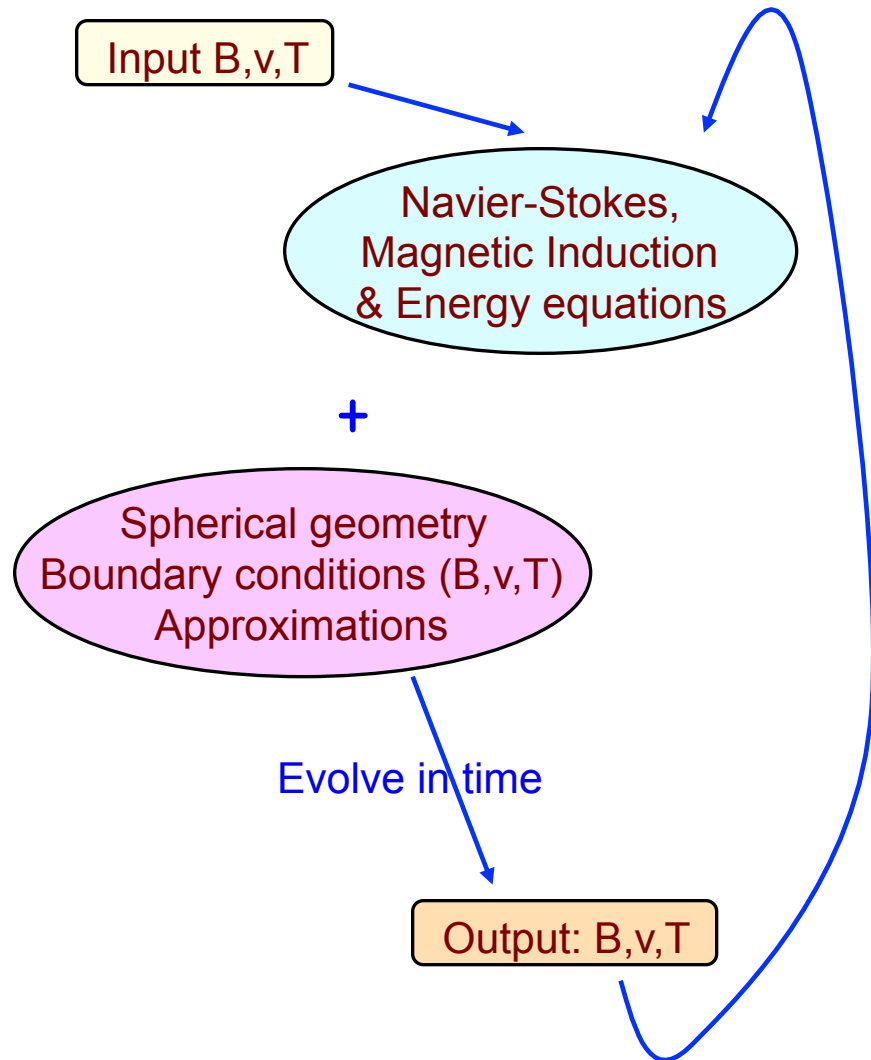


Figure 3 Change in the length of day derived directly from geodetic observations (solid line) and that are predicted from calculations of the core angular momentum derived from geomagnetic observations. The square symbols show the results of Jault et al (1988) and the diamond symbols the results of Jackson et al (1993).



# Numerical Models:

## The Process

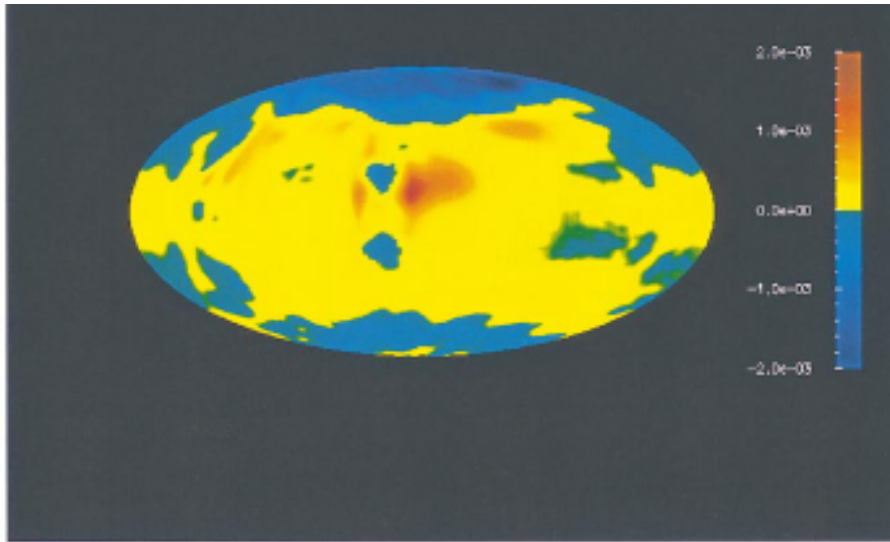


## Characteristics

- geometry:  $r_{io} = \frac{r_i}{r_o}$
- small viscosity:  $E = \frac{\nu}{2\Omega r_o^2} \ll 1$
- small inertia:  $Ro = \frac{\eta}{2\Omega r_o^2} \ll 1$
- strong convection:  $Ra = \frac{\alpha g_o \Delta T r_o}{2\Omega \eta} \gg Ra_c$

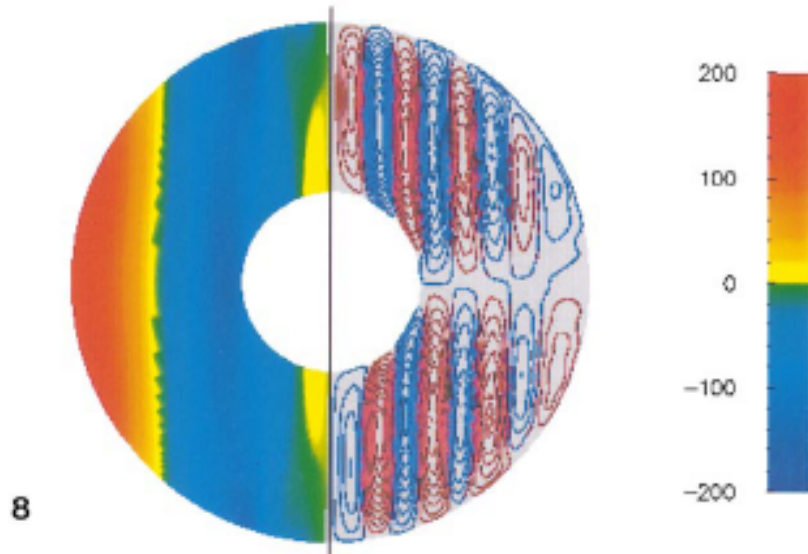
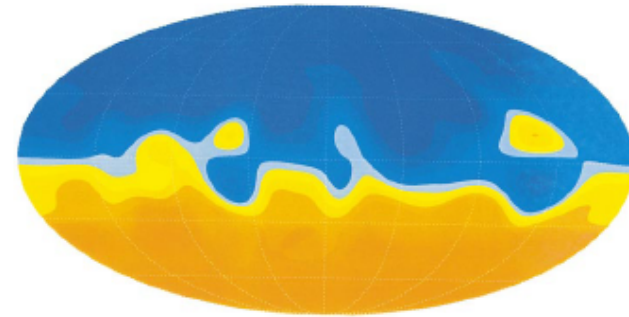
# Results from dynamo models

(KB) weak field dynamo

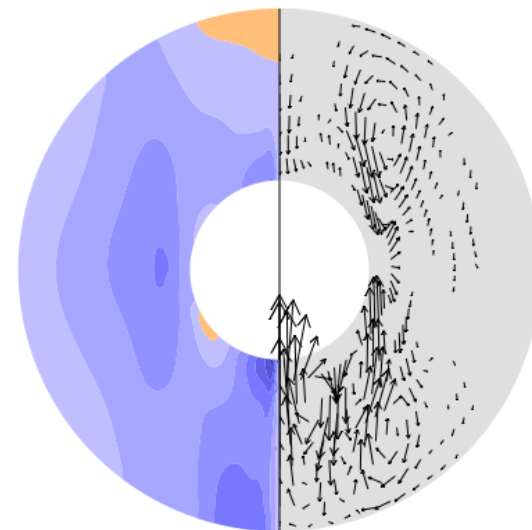


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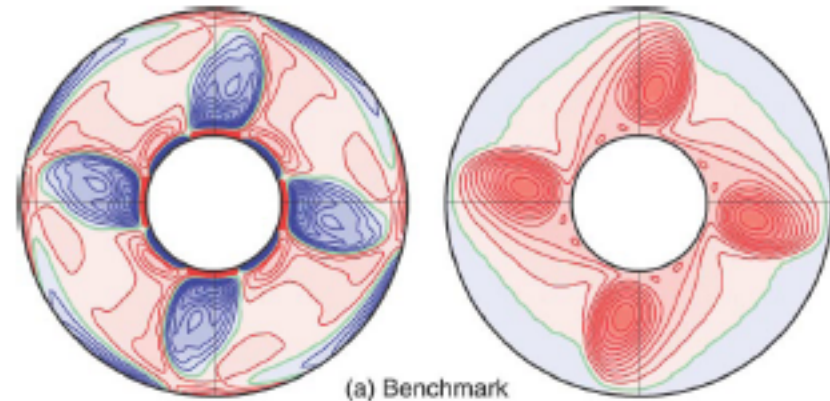
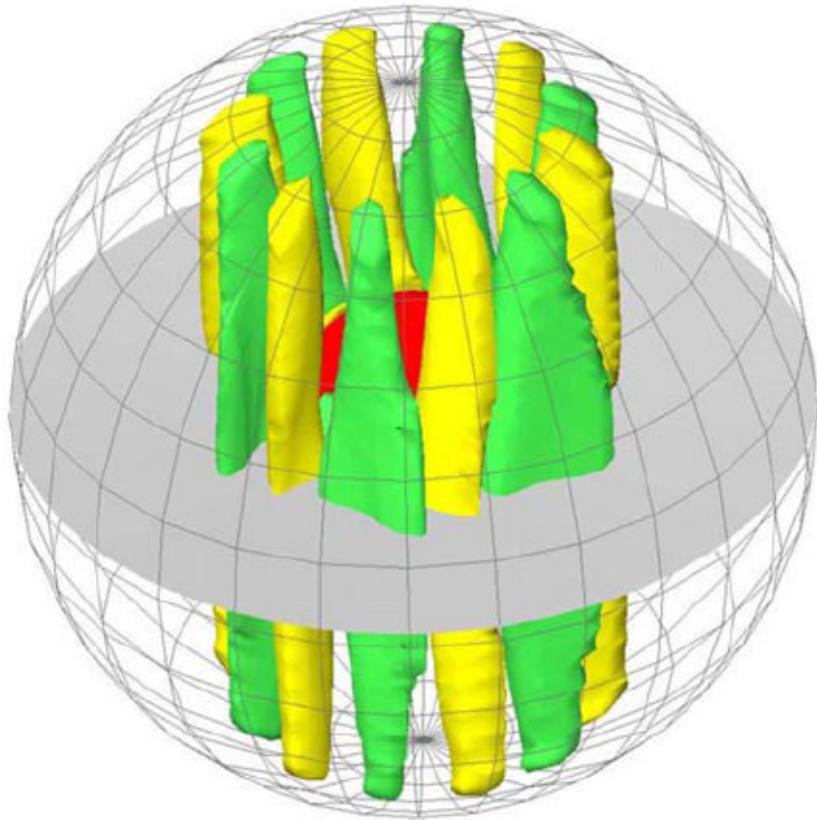
(KB) strong field dynamo



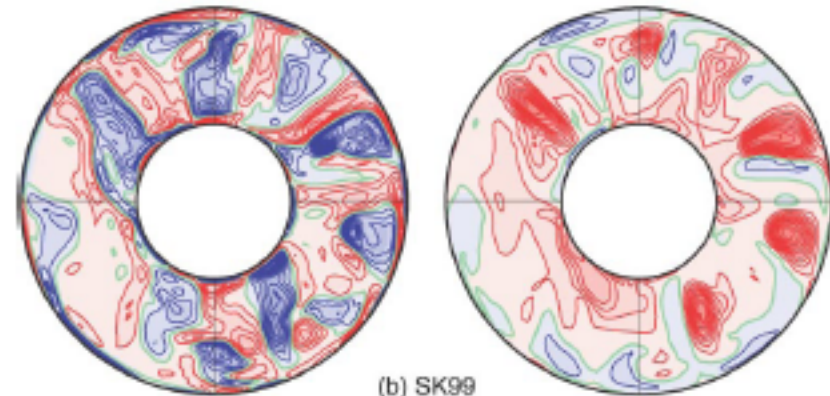
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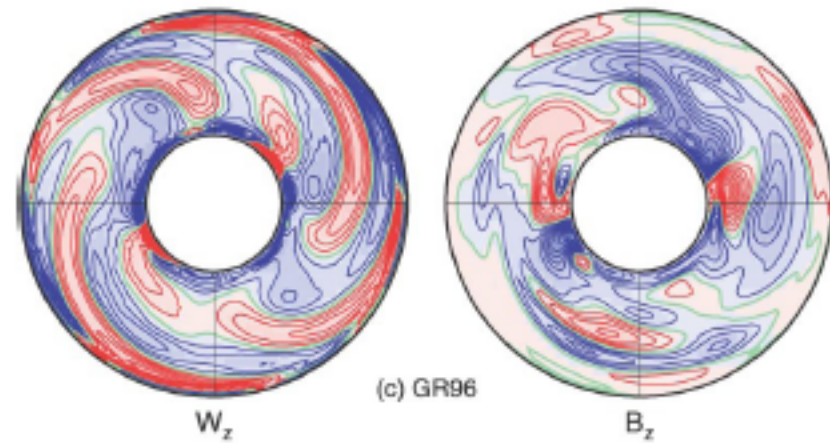
# convection cells in dynamo models



(a) Benchmark



(b) SK99

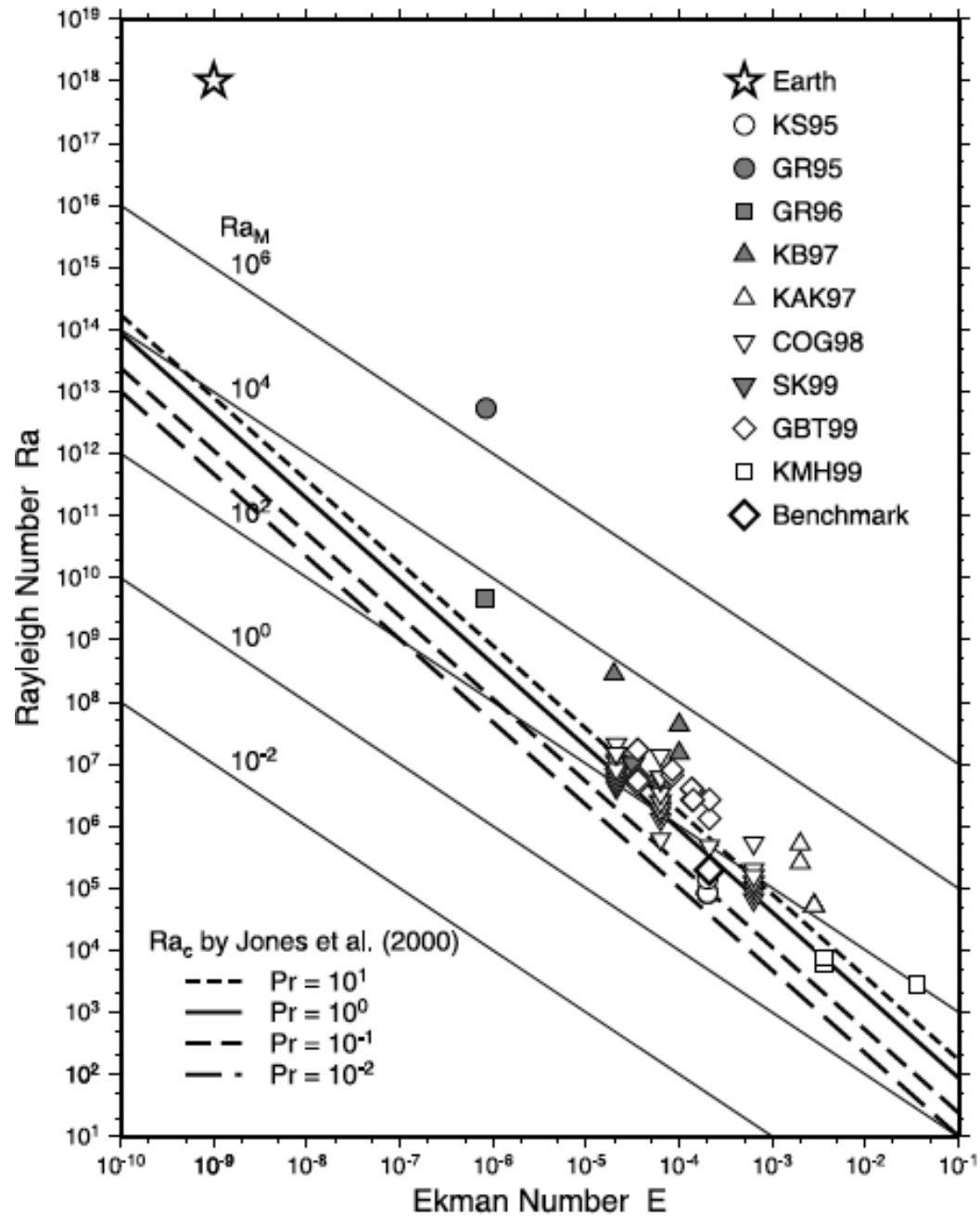


(c) GR96

$W_z$

$B_z$

# How far are we?



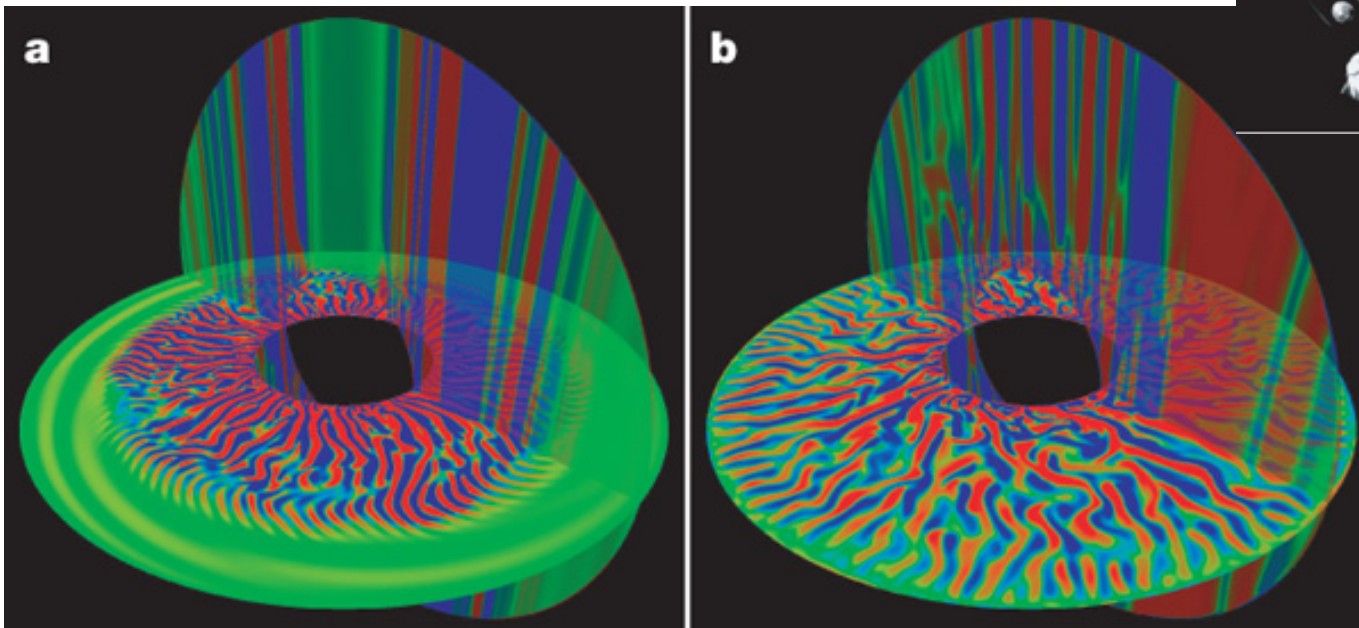
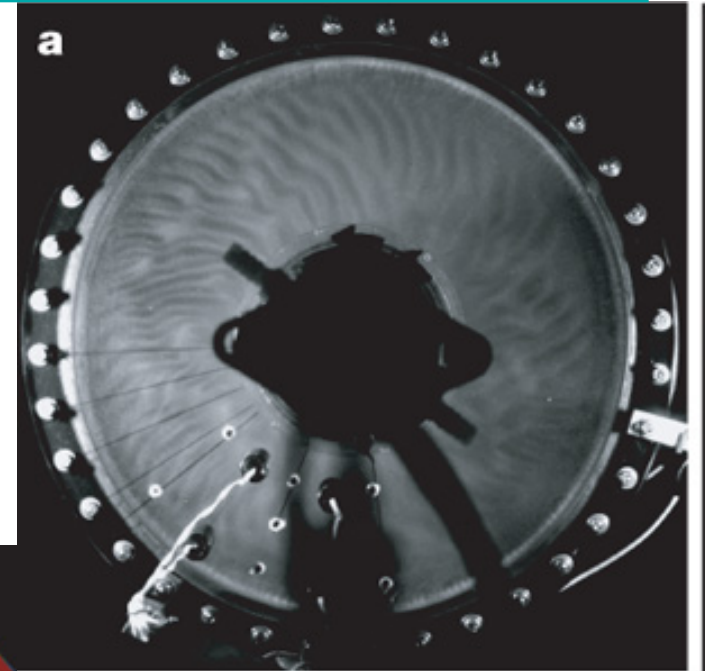


# Convection cells in dynamo models

A Kageyama *et al.* *Nature* 2008

Using the Earth Simulator:  
(but not equilibrated yet,  
magnetic field weak)

axial component of the vorticity



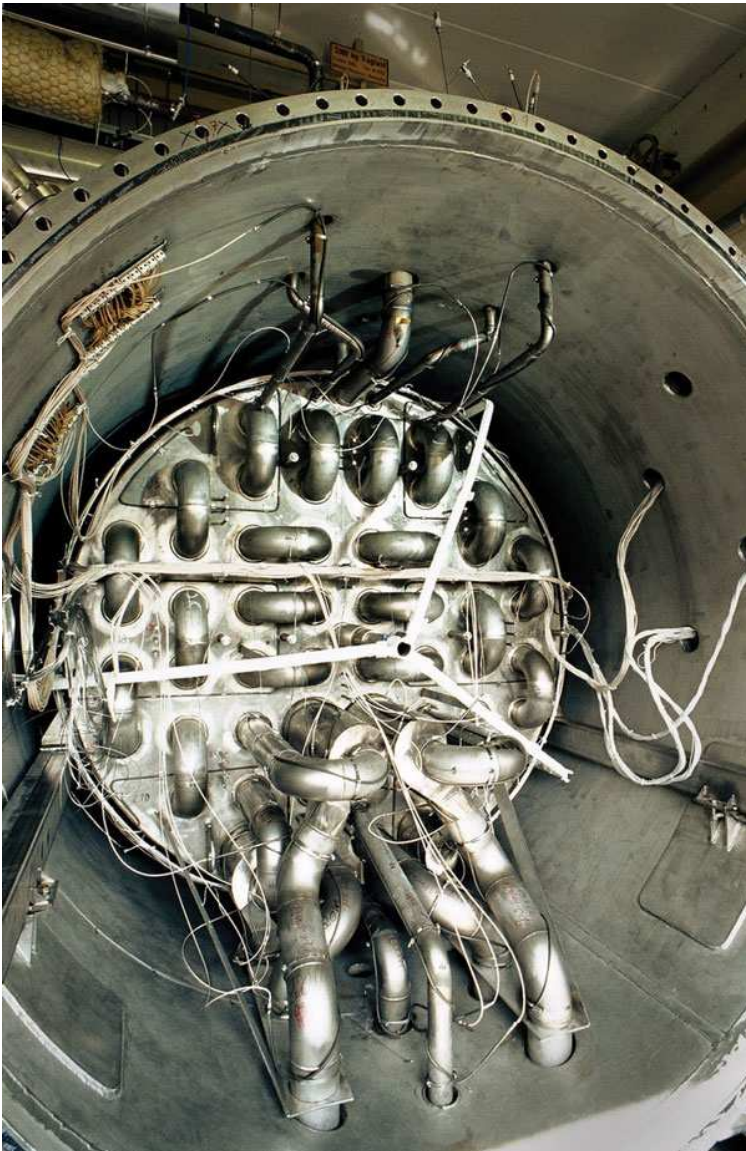
similar to  
experiments

$E=2.3 \times 10^{-7}$ : (lowest ever achieved),  $E=2.6 \times 10^{-6}$

## Experiments:

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Karlsruhe dynamo



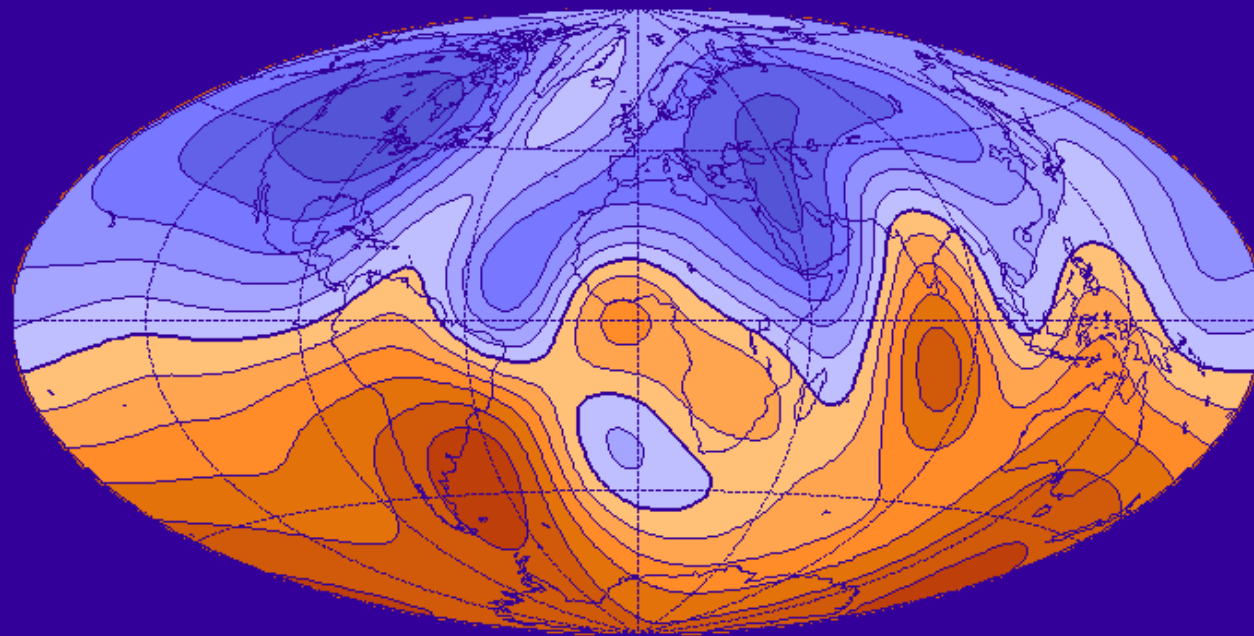
Dan Lathrop's planetary dynamo



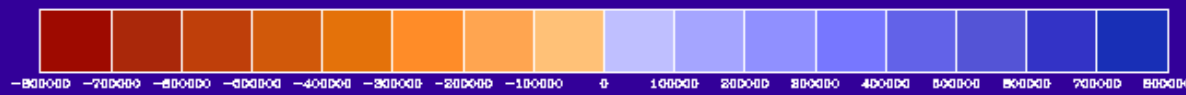


# Case Study: Earth's dynamo

1590



Contour interval =  $10^5$





# Earth-like Numerical Model:

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